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HG1M12: Engineering Mathematics 2

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Outline

1 Vectors

- 2 Calculus of Functions of Two Variables
- 3 Ordinary Differential Equations
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 - 3.2 Order of an ODE
 - 3.3 Linearity
 - 3.4 First-order ODEs
 - 3.6 First order linear equations
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3 Ordinary Differential Equations3.1 Introduction

An ordinary differential equation (ODE) is an equation involving an unknown function, y(x) say, and its derivatives; for example,

$$\frac{dy}{dx} = y$$
, or $\frac{d^2y}{dx^2} + 4\frac{dy}{dx} + 6y = 0$.

• AIM: to learn how to solve ODEs to determine the unknown function y(x).

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Notation: *y* is called the 'dependent' variable, and *x* is the 'independent' variable. Other notations are possible, such as an ODE for *x* as a function of *t*, e.g. $3\frac{d^2x}{dt^2} + 5\frac{dx}{dt} + 7x = 0.$

 ODEs arise quite naturally in a wide variety of practical engineering situations. Some examples of this now follow...

3.1.1 Motion of a mass on a spring in a resistive medium

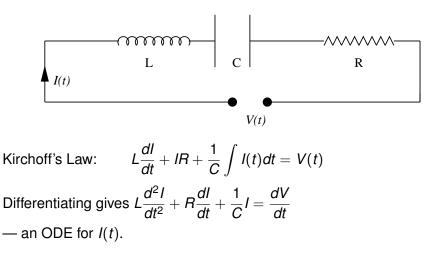
 $x = 0 \qquad x = X(t)$ Resistive force: $-k_1 \times (\text{speed}) = -k_1 \frac{dX}{dt}$, Spring restoring force: $-k_2 \times (\text{extension}) = -k_2(X - I)$, where k_1 and k_2 are constants and *I* is the natural length of the spring.

3.1.1 Motion of a mass on a spring in a resistive medium

 $\begin{array}{ll} x=0 & x=X(t)\\ \text{Resistive force:} & -k_1\times(\text{speed})=-k_1\frac{dX}{dt},\\ \text{Spring restoring force:} & -k_2\times(\text{extension})=-k_2(X-I),\\ \text{where }k_1 \text{ and }k_2 \text{ are constants and }I \text{ is the natural length of the spring.}\\ \text{Newton's Second Law }(F=ma=m\ddot{x}) \Rightarrow \end{array}$

$$-k_1\frac{dX}{dt}-k_2(X-l)=m\frac{d^2X}{dt^2}$$

i.e.
$$m\frac{d^2X}{dt^2} + k_1\frac{dX}{dt} + k_2X = k_2I$$



The rate of decrease of temperature of a body is proportional to the temperature difference between the body and the surrounding air

that is,
$$\frac{dT}{dt} \propto T - T_0$$
 or, equivalently $\frac{dT}{dt} = -k(T - T_0)$

for some constant k.

3.1.4 Free fall under gravity with air resistance

 $R \qquad A \text{ mass } m \text{ falls a distance } y(t),$ and has downward speed $V(t) = \frac{dy}{dt}$ Resistive force, $R \propto V^2 \Rightarrow R = kV^2, (k > 0)$ $F = ma \Rightarrow mg - R = m\frac{dV}{dt}$ mg $\Rightarrow m\frac{dV}{dt} = mg - kV^2$ for V = V(t).

We can rewrite this in other ways: • for y as a function of t, using y(t)

$$V = rac{dy}{dt} \Rightarrow m rac{d^2 y}{dt^2} = mg - k \left(rac{dy}{dt}
ight)^2$$

• for V as a function of y, that is V(y),

using
$$\frac{d}{dt} = \frac{dy}{dt}\frac{d}{dy} = V\frac{d}{dy}$$
 implies $mV\frac{dV}{dy} = mg - kV^2$

The order of an ODE is the highest derivative occurring in the equation. For example,

$$rac{d^2 y}{dx^2} + 6rac{dy}{dx} - 10y = 0$$
 is **second**-order;
 $3rac{dy}{dx} + 4y^3x = 0$ is **first**-order.

We only consider first and second-order ODEs in this module, though some of the ideas carry over to higher-order examples.

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- An ODE is 'linear' if (a) the only y-dependent terms are y itself and derivatives of y and (b) these terms do not appear multiplied together.
- ODEs containing products of y-dependent terms, or functions of y, are said to be 'nonlinear'.

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Examples

■ $\frac{d^2y}{dx^2} + 5\left(\frac{dy}{dx}\right)^3 - 4y = \exp(x)$ is second-order and **nonlinear** (due to the $\left(\frac{dy}{dx}\right)^3$ term),

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Examples

$$\frac{d^2 y}{dx^2} + 5 \left(\frac{dy}{dx}\right)^3 - 4y = \exp(x) \text{ is second-order and nonlinear}$$
(due to the $\left(\frac{dy}{dx}\right)^3$ term), whilst
$$\frac{d^2 y}{dx^2} + 10 \frac{dy}{dx} - 6y = 0 \qquad \text{is second-order}$$
and linear;

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Examples

$$\frac{d^2y}{dx^2} + 5\left(\frac{dy}{dx}\right)^3 - 4y = \exp(x) \text{ is second-order and nonlinear}$$
(due to the $\left(\frac{dy}{dx}\right)^3$ term), whilst

$$\frac{d^2y}{dx^2} + 10\frac{dy}{dx} - 6y = 0$$
is second-order
and linear;

$$y\frac{dy}{dx} + x^3 = 0 \text{ is first-order and nonlinear}$$
(due to the term $y\frac{dy}{dx}$), whilst

$$\frac{dy}{dx} + 4x^3y = e^{4x}$$
is first-order
and linear.

Notice that the coefficients in the ODE might depend upon the independent variable (x in this case).

First-order ODEs are usually written in the canonical form

$$\frac{dy}{dx}=f(x,y)$$

where *f* is a given function. Sometimes they are written in the equivalent form

$$y'(x)=f(x,y).$$

Not all ODEs can be solved explicitly, we now cover some techniques which enable certain classes to be solved.

In this case, the function f 'separates' into the product of a function of x and a function of y. Then we can write f(x, y) = g(x)h(y)

so that the equation becomes $\frac{dy}{dx} = g(x)h(y)$.

We can then rearrange this into the form $\frac{1}{h(y)}\frac{dy}{dx} = g(x)$.

Hence, the solution is obtained by $\int \frac{1}{h(y)} dy = \int g(x) dx + c$,

remembering to include the arbitrary constant of integration c.

Find the general solution of

$$\frac{dy}{dx} = ky.$$

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Solution

$$\frac{dy}{dx} = ky \quad \Rightarrow \quad \int \frac{1}{y} dy = \int k dx + c \quad \Rightarrow \quad \ln y = kx + c.$$

Hence,

$$y = e^{kx+c} = e^c e^{kx} = A e^{kx},$$

where $A = e^c$ is an arbitrary constant.

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3.5.2 Example

Find the general solution of

$$\frac{dy}{dx}=y^{1/2}x.$$

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$$\frac{dy}{dx} = y^{1/2}x.$$

Solution.

$$\frac{dy}{dx} = y^{\frac{1}{2}}x \quad \Rightarrow \quad \int \frac{dy}{y^{\frac{1}{2}}} = \int x dx + c.$$

Hence,

$$2y^{1/2} = \frac{x^2}{2} + c$$
 or $y^{1/2} = \frac{1}{4}(x^2 + A)$,

where A = 2c is an arbitrary constant. Finally,

$$y=\frac{1}{16}\left(x^2+A\right)^2.$$

Find the general solution of $(1 - x^2)\frac{dy}{dx} = -2xe^{-y}$

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Find the general solution of $(1 - x^2)\frac{dy}{dx} = -2xe^{-y}$

Solution This is separable - divide by $(1 - x^2)$ and multiply by e^y . In this case, when the variables have been separated we get

$$\int e^{y} dy = \int \frac{-2x}{(1-x^2)} dx + c.$$

Hence,
$$e^{y} = \ln|1 - x^{2}| + c$$

or, if you prefer,

$$y=\ln\left(\ln|1-x^2|+c\right).$$

It is not always possible to get an explicit expression for y as a function of x. For example:

 $\frac{dy}{dx} = \frac{\cos x}{\sin y}$

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which has the 'solution'

$$-\cos y = \sin x + c.$$

We consider this as the solution, and it represents a family of curves with each member of the family corresponding to a particular value of the constant of integration, *c*.

Recalling our definition of a **linear** differential equation, we see that some of the separable cases that we have studied are nonlinear. For

$$\frac{dy}{dx} = f(x, y)$$

to be linear we must have

$$f(x,y) = -p(x)y + q(x)$$

for given functions p and q. Then the equation becomes

$$\frac{dy}{dx} + p(x)y = q(x).$$

No 'y'-terms are multiplied together and there are no functions of y.

3.6.1 Homogeneous first-order linear ODEs

If q(x) = 0, the equation is said to be **homogeneous**. If q(x) = 0 the equation is also separable. Then

$$rac{dy}{dx} + p(x)y = 0 \quad \Rightarrow \quad rac{dy}{dx} = -p(x)y.$$

Hence,

$$\int \frac{1}{y} dy = -\int p(x) dx + k,$$

where k is a constant of integration, so that

$$\ln y = -\int p(x)dx + k.$$

Taking exponentials, $y = ce^{-\int p(x)dx}$ where $c = e^k$ is an arbitrary constant.

3.6.2 An observation

$$\frac{d}{dx}\left(y(x)\,e^{\int p(x)dx}\right) = e^{\int p(x)dx}\frac{dy}{dx} + y\frac{d}{dx}e^{\int p(x)dx}$$
$$= e^{\int p(x)dx}\frac{dy}{dx} + ye^{\int p(x)dx}\left(\frac{d}{dx}\int p(x)dx\right)$$
$$= e^{\int p(x)dx}\frac{dy}{dx} + e^{\int p(x)dx}p(x)y$$
$$= e^{\int p(x)dx}\left(\frac{dy}{dx} + p(x)y\right).$$

Hence:

$$e^{\int p(x)dx}\left(\frac{dy}{dx}+p(x)y\right) = \frac{d}{dx}\left(ye^{\int p(x)dx}\right).$$

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3.6.3 The inhomogeneous case

To solve the ODE
$$\frac{dy}{dx} + p(x)y = q(x)$$
,

we multiply both sides by the integrating factor (IF) $e^{\int p(x)dx}$:

$$e^{\int p(x)dx}\left(\frac{dy}{dx}+p(x)y\right)=e^{\int p(x)dx}q(x).$$

From the previous result, we have

$$\frac{d}{dx}\left(ye^{\int p(x)dx}\right)=q(x)e^{\int p(x)dx}.$$

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$$\frac{d}{dx}\left(ye^{\int p(x)dx}\right) = q(x)e^{\int p(x)dx}$$

Now integrate both sides with respect to *x*:

$$ye^{\int p(x)dx} = \int q(x)e^{\int p(x)dx}dx + c.$$

 $\Rightarrow \text{ Final result: } \quad y = e^{-\int p(x)dx} \int q(x)e^{\int p(x)dx}dx + ce^{-\int p(x)dx}dx$

NB. If q(x) = 0, then we get the same result as before.

3.6.4 Example

Find the general solution of
$$\frac{dy}{dx} - 2y = e^x$$
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3.6.4 Example

Find the general solution of $\frac{dy}{dx} - 2y = e^x$.

Solution. We identify p(x) = -2, $q(x) = e^x$ The integrating factor is $e^{\int p(x)dx} = e^{-\int 2dx} = e^{-2x}$

Hence,
$$e^{-2x}\left(\frac{dy}{dx}-2y\right)=e^{-2x}e^x=e^{-x}.$$

Then

$$\frac{d}{dx}(ye^{-2x}) = e^{-x} \Rightarrow ye^{-2x} = \int e^{-x}dx + c$$

$$\Rightarrow ye^{-2x} = -e^{-x} + c \Rightarrow y = -e^{-x}e^{2x} + ce^{2x}.$$

$$\Rightarrow y = -e^{x} + ce^{2x} \text{ for arbitrary constant } c.$$

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3.6.5 Example

Find the general solution of

$$x\frac{dy}{dx} + 2y = 3x^3$$

Find the general solution of
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Solution: divide by the coefficient of $\frac{dy}{dx}$ to obtain $\frac{dy}{dx} + \frac{2}{x}y = 3x^2$ (1)
Identify $p(x) = 2/x$ and hence find the **integrating factor**:

$$e^{\int p(x)dx} = e^{\int \frac{2}{x}dx} = e^{2\ln x} = e^{(\ln x^2)} = x^2.$$

Multiply (1) by **IF** = x^2 :

$$x^{2}\frac{dy}{dx} + 2xy = 3x^{4} \quad \Rightarrow \quad \frac{d}{dx}\left(x^{2}y\right) = 3x^{4}$$
$$\Rightarrow \quad x^{2}y = \frac{3}{5}x^{5} + c \quad \Rightarrow \quad y = \frac{3}{5}x^{3} + \frac{c}{x^{2}}.$$

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3.6.6 Boundary and initial conditions

- We have seen that the solution for a first-order ODE involves one unknown constant. This is called the general solution.
- Generally, the number of unknown constants in the general solution equals the order of the ODE.
- To determine a specific solution, we must find these constants.
- We therefore need as many conditions on the solution as there are unknown constants.
- These conditions usually involve the value of the unknown function and/or some of its derivatives at certain points.
- For a first-order equation we only need one such condition, and this is called a **boundary condition**.
- If the independent variable in the ODE is time t, then we normally specify the condition at time t = 0. Then the boundary condition is called an **initial condition**.

3.6.7 Example

Find the general solution of $\frac{dy}{dx} + \frac{x}{1+x^2}y = x$ and the solution subject to the boundary condition y(1) = 0.

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3.6.7 Example

Find the general solution of $\frac{dy}{dx} + \frac{x}{1+x^2}y = x$ and the solution subject to the boundary condition y(1) = 0. **Solution**. This is a linear ODE with

$$p(x)=\frac{x}{1+x^2}, \qquad q(x)=x.$$

Hence we find the integrating factor

$$\int p(x)dx = \int \frac{x}{1+x^2}dx = \frac{1}{2}\ln(1+x^2) = \ln(1+x^2)^{1/2}$$
$$\Rightarrow e^{\int p(x)dx} = e^{\ln(1+x^2)^{1/2}} = (1+x^2)^{1/2}.$$

The effect of multiplying the ODE by the integrating factor is to put the equation into the form

$$\frac{d}{dx}\left(y\left(1+x^2\right)^{1/2}\right) = x\left(1+x^2\right)^{1/2}$$

3.6.7 Example (ctd)

$$\Rightarrow \quad y\left(1+x^{2}\right)^{1/2} = \int x\left(1+x^{2}\right)^{1/2} dx + c = \frac{1}{3}\left(1+x^{2}\right)^{3/2} + c, \\ \Rightarrow \quad y = \frac{1}{3}\left(1+x^{2}\right) + c\left(1+x^{2}\right)^{-1/2}.$$

This is the general solution to the ODE.

3.6.7 Example (ctd)

$$\Rightarrow y (1+x^2)^{1/2} = \int x (1+x^2)^{1/2} dx + c = \frac{1}{3} (1+x^2)^{3/2} + c,$$

$$\Rightarrow y = \frac{1}{3} (1+x^2) + c (1+x^2)^{-1/2}.$$

This is the general solution to the ODE.

(ii) Suppose that we insist that y = 0 when x = 1. i.e. y(1) = 0. Then

$$\frac{1}{3}(1+1) + c(1+1)^{-\frac{1}{2}} = 0$$

which can be solved to give the value of *c* in this case as $c = -\frac{2\sqrt{2}}{2}$.

The solution for y is then

$$y = \frac{1}{3} \left(1 + x^2 \right) - \frac{2\sqrt{2}}{3} \left(1 + x^2 \right)^{-1/2}$$

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Suppose that a variable current I(t), where *t* is time in seconds, flows through a coil with inductance *L* and a resistor of resistance *R* with an applied voltage *V*, where we assume that *L*, *R* and *V* are constants. Suppose also that the current is zero at time t = 0. Find I(t).

Suppose that a variable current I(t), where *t* is time in seconds, flows through a coil with inductance *L* and a resistor of resistance *R* with an applied voltage *V*, where we assume that *L*, *R* and *V* are constants. Suppose also that the current is zero at time t = 0. Find I(t).

Solution The current satisfies the ODE $L\frac{dI}{dt} + RI = V$

subject to the initial condition I(0) = 0.

We can re-write the ODE in the form

$$\frac{dI}{dt} + \frac{R}{L}I = \frac{V}{L},$$

which is linear, and first-order.

Since p = R/L, the integrating factor is $\exp\left(\int \frac{R}{L} dt\right) = e^{Rt/L}$.

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3.6.8 Example (ctd)

Hence,
$$e^{Rt/L}\left(\frac{dI}{dt} + \frac{R}{L}I\right) = \frac{V}{L}e^{Rt/L} = \frac{d}{dt}\left(e^{Rt/L}I\right) = \frac{V}{L}e^{Rt/L}$$

$$\Rightarrow e^{Rt/L}I = \frac{V}{L}\frac{L}{R}e^{Rt/L} + c,$$

where c is a constant of integration. Hence, the general solution for I is

$$I(t)=\frac{V}{R}+ce^{-Rt/L}.$$

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Hence,
$$e^{Rt/L}\left(\frac{dI}{dt} + \frac{R}{L}I\right) = \frac{V}{L}e^{Rt/L} = \frac{d}{dt}\left(e^{Rt/L}I\right) = \frac{V}{L}e^{Rt/L}$$

 $\Rightarrow e^{Rt/L}I = \frac{V}{L}\frac{L}{R}e^{Rt/L} + c,$

where c is a constant of integration. Hence, the general solution for I is

$$I(t)=\frac{V}{R}+ce^{-Rt/L}.$$

But I(0) = 0, from the initial condition. So $0 = \frac{V}{R} + c \Rightarrow c = -\frac{V}{R}$. Therefore the solution for I(t) is $I(t) = \frac{V}{R} \left(1 - e^{-Rt/L}\right)$.

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The rate of increase of the concentration of a chemical is proportional to the concentration at that time.

Experiment shows that the concentration doubles in four hours. If the initial concentration is c_0 , what is the concentration after five hours?

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Experiment shows that the concentration doubles in four hours. If the initial concentration is c_0 , what is the concentration after five hours?

Solution: Let c(t) denote the concentration at time *t*. Then $\frac{dc}{dt} = kc$, for some constant *k*. This is a separable ODE and so we obtain

$$\int \frac{1}{c} dc = \int k dt + A \quad \Rightarrow \quad \ln c(t) = kt + A \quad \Rightarrow \quad c(t) = Be^{kt}$$

where A and $B = e^{A}$ are constants.

3.6.9 Example (ctd)

Using $c = Be^{kt}$ and the initial condition

$$c = c_0$$
 at $t = 0 \Rightarrow c_0 = Be^0 = B$,

gives

$$c(t)=c_0e^{kt}.$$

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$$\boldsymbol{c}(t)=\boldsymbol{c}_{0}\boldsymbol{e}^{kt}.$$

At t = 4 (in units of hours), $c = 2c_0$. So

$$2c_0 = c_0 e^{4k}$$

or

$$k=\frac{1}{4}\ln 2 \quad \Rightarrow c(t)=c_0e^{(t/4)\ln 2}.$$

3.6.9 Example (ctd)

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$$2c_0 = c_0 e^{4k}$$

or

$$k=rac{1}{4}\ln 2 \quad \Rightarrow c(t)=c_0e^{(t/4)\ln 2}.$$

If t = 5,

$$c(5) = c_0 e^{(5/4) \ln 2} = c_0 e^{\ln 2^{5/4}} = 2^{5/4} c_0$$

We can always express the equation

$$\frac{dy}{dx} = f(x, y)$$

in the form

$$M(x,y)+N(x,y)\frac{dy}{dx}=0,$$

by setting $f(x, y) = -\frac{M(x, y)}{N(x, y)}$, if necessary.

Sometimes the left-hand side in the above equation is an *exact derivative*, in which case the ODE is called **exact** and its solution is easily found. This happens if there exists a function *F*(*x*, *y*) such that

$$\frac{dF(x,y)}{dx} = M(x,y) + N(x,y)\frac{dy}{dx}$$

$$y + x \frac{dy}{dx} = 0 \quad \Leftrightarrow \quad \frac{d}{dx}(xy) = 0,$$

by the product rule (in this case, F = xy). Hence, the solution is xy = c,

where *c* is an arbitrary constant; thus y = c/x.

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$$y + x \frac{dy}{dx} = 0 \quad \Leftrightarrow \quad \frac{d}{dx}(xy) = 0,$$

by the product rule (in this case, F = xy). Hence, the solution is xy = c, where a is an arbitrary constant; thus y = a/x.

where *c* is an arbitrary constant; thus y = c/x.

Example:
$$-\frac{x^2}{y^2}\frac{dy}{dx} + \frac{2x}{y} = 0 \Rightarrow \frac{d}{dx}\left(\frac{x^2}{y}\right) = 0. \Rightarrow \frac{x^2}{y} = c,$$

where c is an arbitrary constant, hence

$$y=\frac{x^2}{c}=Ax^2, \ A=\frac{1}{c}.$$

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3.7.2 Conditions for exact derivatives

Suppose
$$M(x, y) + N(x, y)\frac{dy}{dx} = 0$$

is equivalent to $\frac{d}{dx}(F(x, y)) = 0.$ (*)

.

Then since

$$\frac{d}{dx}\left(F(x,y(x))\right) = \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y}\frac{dy}{dx}$$

we must have that

$$\frac{\partial F}{\partial x} = M$$
 and $\frac{\partial F}{\partial y} = N$.

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$$M(x, y) + N(x, y)\frac{dy}{dx} = 0$$

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Then since

$$\frac{d}{dx}\left(F(x,y(x))\right) = \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y}\frac{dy}{dx}$$

we must have that

$$\frac{\partial F}{\partial x} = M \quad \text{and} \quad \frac{\partial F}{\partial y} = N.$$

Since $\frac{\partial^2 F}{\partial y \partial x} = \frac{\partial^2 F}{\partial x \partial y}$, we must also have $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$.

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$$\frac{\partial F}{\partial x} = M \quad \text{and} \quad \frac{\partial F}{\partial y} = N.$$
Since $\frac{\partial^2 F}{\partial y \partial x} = \frac{\partial^2 F}{\partial x \partial y}$, we must also have $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}.$
Integrating (*), the solution is $F(x, y) = c$, where *c* is a constant.

We revisit the problem:
$$y + x \frac{dy}{dx} = 0$$

$$M(x,y) = y, \ N(x,y) = x \Rightarrow \frac{\partial M}{\partial y} = 1 = \frac{\partial N}{\partial x}.$$

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 $M = F_x, N = F_y$

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$$y + x \frac{dy}{dx} = 0$$

$$M(x,y) = y, \ N(x,y) = x \quad \Rightarrow \quad \frac{\partial M}{\partial y} = 1 = \frac{\partial N}{\partial x}.$$

 $M = F_x, N = F_y \text{ also implies} \quad \frac{\partial F}{\partial x} = y \quad \text{and} \quad \frac{\partial F}{\partial y} = x.$ $\frac{\partial F}{\partial x} = y \quad \Rightarrow \quad F = xy + g(y).$ $\frac{\partial F}{\partial y} = x \quad \Rightarrow \quad \frac{\partial}{\partial y} (xy + g(y)) = x$

$$\Rightarrow$$
 $g'(y) = 0$ or $g(y) =$ const.

So
$$F(x, y) = xy + \text{constant}$$

and the general solution is xy = constant, as before.

Let us revisit the problem
$$-\frac{x^2}{y^2}\frac{dy}{dx} + \frac{2x}{y} = 0$$

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$$-\frac{x^2}{y^2}\frac{dy}{dx} + \frac{2x}{y} = 0$$

Hence
$$M(x, y) = \frac{2x}{y}$$
, $N(x, y) = -\frac{x^2}{y^2}$.
Check solvability: $\frac{\partial M}{\partial y} = -\frac{2x}{y^2} = \frac{\partial N}{\partial x}$.

Let us revisit the problem
$$-\frac{x^2}{y^2}\frac{dy}{dx} + \frac{2x}{y} = 0$$

Hence
$$M(x, y) = \frac{2x}{y}$$
, $N(x, y) = -\frac{x^2}{y^2}$.

Check solvability:	∂M	2 <i>x</i>	∂N
	$\frac{\partial y}{\partial y} =$	$-\overline{y^2} =$	$=\overline{\partial x}$.

Solve:
$$\frac{\partial F}{\partial x} = \frac{2x}{y} \Rightarrow F = \frac{x^2}{y} + g(y).$$
 (*)
 $\frac{\partial F}{\partial y} = -\frac{x^2}{y^2} \Rightarrow \frac{\partial}{\partial y} \left(\frac{x^2}{y} + g(y)\right) = -\frac{x^2}{y^2}.$
Hence, $g'(y) = 0 \Rightarrow g(y) = \text{constant.}$

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Let us revisit the problem
$$-\frac{x^2}{y^2}\frac{dy}{dx} + \frac{2x}{y} = 0$$

Hence
$$M(x, y) = \frac{2x}{y}$$
, $N(x, y) = -\frac{x^2}{y^2}$.

Check solvability:	∂M	2 <i>x</i>	∂N
	$\overline{\partial y} =$	$-\overline{y^2}$ =	$=\overline{\partial x}$.

Solve:
$$\frac{\partial F}{\partial x} = \frac{2x}{y} \Rightarrow F = \frac{x^2}{y} + g(y).$$
 (*)
 $\frac{\partial F}{\partial y} = -\frac{x^2}{y^2} \Rightarrow \frac{\partial}{\partial y} \left(\frac{x^2}{y} + g(y)\right) = -\frac{x^2}{y^2}.$

Hence, $g'(y) = 0 \Rightarrow g(y) =$ constant.

Therefore, from (*), $F(x, y) = x^2/y + \text{constant}$ and so the general solution F(x, y) = constant implies $x^2/y = \text{constant}$.

3.7.5 New example

Check the solvability and, if possible, solve $2xy + (x^2 - 1) \frac{dy}{dx} = 0$

3.7.5 New example

Check the solvability and, if possible, solve $2xy + (x^2 - 1)\frac{dy}{dx} = 0$ Solution: M(x, y) = 2xy, $N(x, y) = x^2 - 1 \Rightarrow \frac{\partial M}{\partial y} = 2x = \frac{\partial N}{\partial x}$.

3.7.5 New example

Check the solvability and, if possible, solve $2xy + (x^2 - 1) \frac{dy}{dx} = 0$

Solution:
$$M(x,y) = 2xy$$
, $N(x,y) = x^2 - 1 \Rightarrow \frac{\partial M}{\partial y} = 2x = \frac{\partial N}{\partial x}$.

We know that the equation must be equivalent to $\frac{d}{dx}(F(x, y(x)) = 0)$

where
$$\frac{\partial F}{\partial x} = 2xy$$
 and $\frac{\partial F}{\partial y} = x^2 - 1$.
 $\frac{\partial F}{\partial x} = 2xy \Rightarrow F = x^2y + g(y)$.
Therefore $\frac{\partial F}{\partial y} = x^2 + g'(y) = x^2 - 1$
 $\Rightarrow g'(y) = -1$, implying $g(y) = -y + \text{const.}$
So $F(x, y) = \text{constant} \Rightarrow x^2y - y = c$.
This can be re-expressed in the form $y = \frac{c}{x^2 - 1}$.

This

We restrict attention to second-order ODEs of the general form

$$a\frac{d^2y}{dx^2}+b\frac{dy}{dx}+cy=f(x),$$

where *a*, *b* and *c* are given constants.

- These are called *constant coefficient, linear second-order ODEs*.
- If f(x) = 0, the right-hand side is zero and the ODE is referred to as homogeneous; we consider these first.
- Other notation is possible; for example, the ODE might be in terms of x(t) and its derivatives with respect to t.

3.8.1 Simpler case

The case a = 0.

$$b\frac{dy}{dx}+cy=0$$

and we know how to solve this (by separating the variables). The solution is

$$y = Ae^{-cx/b}$$
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.

Alternatively, try $y = Ae^{mx}$ as a solution.

$$b\frac{dy}{dx} + cy = 0 \quad \Rightarrow \quad bmAe^{mx} + cAe^{mx} \quad \Rightarrow \quad Ae^{mx}(bm+c) = 0.$$

Hence,

$$m = -\frac{c}{b}$$

and we have obtained the same answer as before.

Suppose we adopt the same approach for the second-order equation:

$$y = Ae^{mx} \Rightarrow \frac{dy}{dx} = mAe^{mx}, \frac{d^2y}{dx^2} = m^2Ae^{mx}.$$

Substituting into the ODE, we find

$$am^2Ae^{mx} + bmAe^{mx} + cAe^{mx} = 0$$

 $\Rightarrow Ae^{mx}(am^2 + bm + c) = 0.$
 $Ae^{mx} \neq 0 \Rightarrow am^2 + bm + c = 0.$

So *m* satisfies a quadratic equation called the **auxiliary equation**.

If the two roots are m_1 and m_2 , then the general solution for y is

 $y = Ae^{m_1x} + Be^{m_2x},$

where A and B are arbitrary constants.

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where A and B are arbitrary constants.

Example: Solve $\frac{d^2y}{dx^2} - \frac{dy}{dx} - 2y = 0$ $y = Ae^{mx} \Rightarrow Ae^{mx}(m^2 - m - 2) = 0$ $\Rightarrow m^2 - m - 2 = 0 \Rightarrow (m + 1)(m - 2) = 0$ $\Rightarrow m_1 = -1, m_2 = 2.$

The general solution for y is $y = Ae^{-x} + Be^{2x}$ for arbitrary constants A and B.

Solve
$$\frac{d^2y}{dx^2} - 4\frac{dy}{dx} + 3y = 0$$

Solve
$$\frac{d^2y}{dx^2} - 4\frac{dy}{dx} + 3y = 0$$

Solution: $y = Ae^{mx} \Rightarrow Ae^{mx}(m^2 - 4m + 3) = 0$
$$\Rightarrow m^2 - 4m + 3 = 0 \Rightarrow (m - 3)(m - 1) = 0$$
$$\Rightarrow m_1 = 3, m_2 = 1.$$

The general solution for y is $y = Ae^{3x} + Be^{x}$ for arbitrary constants A and B.

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Since m_1 and m_2 are the roots of a quadratic equation, three different cases are possible:

- **1** m_1 and m_2 are real and distinct (as in the previous two examples)
- **2** m_1 and m_2 are real and repeated (i.e. $m_1 = m_2$)
- 3 m_1 and m_2 are complex conjugates

We now consider the second and third cases, the first having already been dealt with.

2 If $m_1 = m_2$, the general solution would appear to be

$$y = Ae^{m_1x} + Be^{m_2x} = Ce^{m_1x}$$

where C = A + B. The solution now only contains one constant of integration, and we know that it should contain two.

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$$y=(A+Bx)e^{m_1x},$$

where A and B are arbitrary constants.

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where A and B are arbitrary constants.

Example: Solve y'' - 6y' + 9y = 0 $y = Ae^{mx} \Rightarrow Ae^{mx}(m^2 - 6m + 9) = 0 \Rightarrow (m - 3)^2 = 0.$

So m = 3 is repeated and the general solution is $y = (A + Bx) e^{3x}$.

3 Suppose the roots are

$$m_1 = \alpha + i\beta, \quad m_2 = \alpha - i\beta.$$

The general solution for y is now

$$y = Ae^{(\alpha+i\beta)x} + Be^{(\alpha-i\beta)x} = Ae^{\alpha x}e^{i\beta x} + Be^{\alpha x}e^{-i\beta x}$$

= $e^{\alpha x}(Ae^{i\beta x} + Be^{-i\beta x}) = e^{\alpha x}((A+B)\cos(\beta x) + i(A-B)\sin(\beta x))$
= $e^{\alpha x}(C\cos(\beta x) + D\sin(\beta x))$,

where C and D are arbitrary constants (they are, in fact, combinations of A and B.) This is the general solution in this case.

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Find the general solution of $\frac{d^2y}{dx^2} + y = 0$

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- Find the general solution of $\frac{d^2y}{dx^2} + y = 0$
- The auxiliary equation is $m^2 + 1 = 0$,

so that the solutions are $m_1 = i$ and $m_2 = -i$; that is $\alpha = 0$, $\beta = 1$.

So the general solution in this case is $y = C \cos x + D \sin x$.

3.9.6 SUMMARY: 2nd-order homogeneous ODEs

The **GENERAL SOLUTION** of the ODE

$$a\frac{d^2y}{dx^2} + b\frac{dy}{dx} + cy = 0$$

is found by solving the **auxiliary equation** $am^2 + bm + c = 0$, then

 y = Ae^{m₁x} + Be^{m₂x} if m₁ and m₂ are the **distinct** roots of the auxiliary equation
 y = (A + Bx) e^{m₁x} if m₂ = m₁ are **repeated** roots of the auxiliary equation
 y = e^{αx} (Acos(βx) + Bsin(βx)) if m₁ = α + iβ and m₂ = α - iβ are **complex conjugate** roots of the auxiliary equation.

In all cases, A and B are *arbitrary real constants* (for convenience, in the final case, we have reverted to A and B instead of C and D).

3.10 The inhomogeneous case

The linear ODE

$$a\frac{d^2y}{dx^2} + b\frac{dy}{dx} + cy = r(x)$$

is said to be **inhomogeneous**, i.e. there is a term involving *x* but not *y* on the RHS.

This equation is solved in two stages:

3.10 The inhomogeneous case

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$$a\frac{d^2y}{dx^2} + b\frac{dy}{dx} + cy = r(x)$$

is said to be **inhomogeneous**, i.e. there is a term involving x but not y on the RHS.

This equation is solved in two stages:

1 Consider the equivalent homogeneous equation obtained by setting r(x) = 0,

$$a\frac{d^2y}{dx^2} + b\frac{dy}{dx} + cy = 0$$

Solve this using the previous method;

This solution is called the **complementary function** (C.F.) written u(x) say.

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3.10 Inhomogeneous ODEs (ctd)

Obtain (for example by trial and error) a particular solution to the original inhomogeneous equation, or particular integral (P.I.), written v(x) say.

Note: Usually, the form of the P.I. is closely related to the function r(x). We can use our experience of derivatives of functions to help find v(x). For example differentiating

- e^{px} gives pe^{px} (use if RHS is an exponential)
- x^n gives nx^{n-1} (use if RHS is a polynomial)
- sin px gives p cos px (use if RHS is sin / cos)
- $\cos px$ gives $-p \sin px$ (use if RHS is \sin / \cos)

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- x^n gives nx^{n-1} (use if RHS is a polynomial)
- sin px gives p cos px (use if RHS is sin / cos)
- $\cos px$ gives $-p \sin px$ (use if RHS is \sin / \cos)

The complete general solution is then

y=u(x)+v(x)

Find the general solution of

$$\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = e^{-x}.$$

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Find the general solution of $\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = e^{-x}$.

First solve the equivalent homogeneous equation is set RHS to zero.

Auxiliary equation is

$$m^2 - 3m + 2 = 0$$

with solutions m = 1, m = 2.

Hence the complementary function is

$$u(x)=Ae^{x}+Be^{2x}.$$

Now seek a particular solution related to $r(x) = e^{-x}$. Try a solution of the form

$$v(x) = Ce^{-x}$$

3.10.1 Example (ctd)

then

$$\frac{dv}{dx} = -Ce^{-x}$$
 and $\frac{d^2v}{dx^2} = Ce^{-x}$.

Substitute into the ODE:

$$Ce^{-x} - 3(-Ce^{-x}) + 2Ce^{-x} = e^{-x}.$$

ie

$$6Ce^{-x}=e^{-x}.$$

Equating the coefficients of e^{-x} we obtain C = 1/6. So the P.I. is

$$v(x)=\frac{1}{6}e^{-x}.$$

The general solution to the ODE is the C.F. plus the P.I.:

$$y = Ae^{x} + Be^{2x} + \frac{1}{6}e^{-x}.$$

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3.10.2 Example

Find the general solution of

$$\frac{d^2y}{dx^2}-3\frac{dy}{dx}+2y=3-2x^2.$$

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Find the general solution of

$$\frac{d^2y}{dx^2}-3\frac{dy}{dx}+2y=3-2x^2.$$

Since the LHS is the same as example (9), the C.F. is the same. Now find the P.I.:

since
$$r(x) = 3 - 2x^2$$
, try
 $v(x) = ax^2 + bx + c$.

and find appropriate values for *a*, *b* and *c*.

Now

$$\frac{dv}{dx} = 2ax + b, \qquad \frac{d^2v}{dx^2} = 2a.$$

Substitute into the ODE:

$$2a - 3(2ax + b) + 2(ax^2 + bx + c) = 3 - 2x^2.$$

Collecting terms

$$2ax^{2} + x(-6a + 2b) + (2a - 3b + 2c) = 3 - 2x^{2}.$$

Now find *a*, *b* and *c* by equating coefficients: $x^2: 2a = -2 \Rightarrow a = -1.$ $x^1: -6a + 2b = 0 \Rightarrow b = -3.$ $x^0: 2a - 3b + 2c = 3 \Rightarrow c = -2.$ So the PI is $v(x) = -x^2 - 3x - 2.$ So the complete general solution to the ODE is (CF+PI):

$$y = Ae^{x} + Be^{2x} - x^{2} - 3x - 2.$$

$$\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = \sin x.$$

Again the C.F. is the same as before.

Try to find a P.I. of the form $v(x) = a \sin x$ and find an appropriate value of *a*.

When we substitute into the ODE we obtain

 $-a\sin x - 3a\cos x + 2a\sin x = \sin x.$

- Collecting terms: $a \sin x 3a \cos x = \sin x$
- Now equate coefficients of sin x and of cos x: there is no value of a which will make both

 $a \sin x = \sin x$ and $-3a \cos x = 0$.

So need to try a different form for the PI.

3.10.3 Example (ctd)

So, try a P.I. of the form

 $v(x) = a \sin x + b \cos x$ and find appropriate values for *a* and *b*.

Substituting into the ODE we obtain

 $-a\sin x - b\cos x - 3a\cos x + 3b\sin x + 2a\sin x + 2b\cos x = \sin x.$

Collecting terms $(a+3b)\sin x + (b-3a)\cos x = \sin x.$

Now equate coefficients: $\cos x: \quad b-3a=0 \Rightarrow b=3a.$ $\sin x: \quad a+3b=1 \Rightarrow a+9a=1.$

Solving for *a* and *b*, a = 1/10, b = 3/10.So the solution to the ODE is:

$$y = Ae^{x} + Be^{2x} + \frac{1}{10}\sin x + \frac{3}{10}\cos x.$$

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Note: this method may fail if the RHS is the same for as the CF.

$$\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = e^x$$

This is an example of an *exceptional case:* the function $r(x) = e^x$ appears in the C.F. $u(x) = Ae^x + Be^{2x}$.

In this case the natural first choice for the P.I.,

$$v(x) = ae^x$$
,

fails, as it gives

$$ae^{x} - 3ae^{x} + 2ae^{x} = e^{x} \Rightarrow 0 = 1$$
 ??

The solution is to try a P.I. of the form $v(x) = axe^x$.

Then

$$\frac{dv}{dx} = axe^x + ae^x, \qquad \frac{d^2v}{dx^2} = axe^x + 2ae^x$$

Substitute into the ODE:

$$axe^{x} + 2ae^{x} - 3(axe^{x} + ae^{x}) + 2axe^{x} = e^{x}$$
.

Now all the terms in xex cancel out, leaving

$$2ae^{x}-3ae^{x}=e^{x}$$
 \Rightarrow $a=-1$,

so the solution to the ODE is

$$y = Ae^x + Be^{2x} - xe^x.$$

Similar modifications with other exceptional cases.

G Adesso (University of Nottingham)

In general, the solution to an *n*th order ODE contains *n* arbitrary constants. To determine the values of these constants, *n* additional conditions must be specified. For a second-order equation two additional conditions are needed, and they can be either

Initial Conditions

If two conditions (usually y and y') are given at the same value of x (e.g. x = 0)

or

Boundary Conditions

If one condition is given at $x = x_1$ (say) and the second condition is given at $x = x_2$ (say), or perhaps a limit as $x \to \infty$.

3.11.1 Example

$$\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = e^x$$

with the initial conditions

$$y = 1$$
 and $\frac{dy}{dx} = 0$ at $x = 0$.

The general solution to the ODE is

$$y = Ae^x + Be^{2x} - xe^x,$$

from the previous example. At x = 0,

$$y = A + B = 1$$
 and $\frac{dy}{dx} = A + 2B - 1 = 0.$

Hence A = 1 and B = 0, so the solution to the ODE with these initial conditions is

$$y = e^x - xe^x$$
.

3.12.1 Miscellaneous examples

Find the curve in the (x, y) plane that passes through (0,3) and whose tangent line at a point (x, y) has slope $2x/y^2$.

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3.12.1 Miscellaneous examples

Find the curve in the (x, y) plane that passes through (0,3) and whose tangent line at a point (x, y) has slope $2x/y^2$.

Since the slope of the curve y = y(x) is $\frac{dy}{dx}$, we have $\frac{dy}{dx} = \frac{2x}{y^2}$

and since it must pass through (0,3) we have the condition y(0) = 3. Separating the variables, we find $\int y^2 dy = \int 2x dx + c$ where c is an arbitrary constant. Hence $\frac{1}{3}y^3 = x^2 + c$.

$$y(0) = 3 \Rightarrow \frac{1}{3}3^3 = 0 + c$$
 so $c = 9$.

Finally

$$\frac{1}{3}y^3 = x^2 + 9$$
 or $y = (3x^2 + 27)^{\frac{1}{3}}$

3.12.2 The LCR circuit revisited

Recall that the ODE for the current I(t) flowing around a circuit with an applied voltage V(t) in the presence of a resistance R, capacitance C and inductance L is

$$L\frac{d^2I}{dt^2} + R\frac{dI}{dt} + \frac{1}{C}I = \frac{dV}{dt}$$

So if V(t) is constant, this becomes

$$L\frac{d^2I}{dt^2} + R\frac{dI}{dt} + \frac{1}{C}I = 0.$$

If we seek a solution $I(t) = Ae^{mt}$ then m satisfies the auxiliary equation

$$Lm^2+Rm+\frac{1}{C}=0.$$

This has solutions

G Adesso

$$m_{1} = \frac{-R + \sqrt{R^{2} - 4\frac{L}{C}}}{2L} \text{ and } m_{2} = \frac{-R - \sqrt{R^{2} - 4\frac{L}{C}}}{\frac{2L}{2L}}$$
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lf

$$R^2 - 4\frac{L}{C} > 0$$

then the solutions for m_1 and m_2 are real and the solutions are of exponential form and decay with time. However, if

$$R^2 - 4\frac{L}{C} < 0$$

then the solutions are complex and we get oscillatory solutions of the form

$$I(t) = A \exp\left(-\frac{Rt}{2L}\right) \cos\left(\frac{t}{2L}\sqrt{R^2-4\frac{L}{C}}\right).$$

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3.12.3 Example

Solve the ODE y'' - y' - 2y = 0.

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Solve the ODE y'' - y' - 2y = 0. **Solution**: Seeking a solution of the form $y = Ae^{mx}$ gives that *m* satisfies the auxiliary equation

$$m^2-m-2=0.$$

Hence
$$(m-2)(m+1) = 0$$

so m = 2 and m = -1 are the two roots. Hence the general solution is

$$y = Ae^{2x} + Be^{-x}$$

for arbitrary constants A and B.

3.12.4 Example

Solve the ODE y'' + 4y' + 4y = 0.

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Solve the ODE y'' + 4y' + 4y = 0. **Solution**: Seeking a solution of the form $y = Ae^{mx}$ gives that *m* satisfies the auxiliary equation

$$m^2 + 4m + 4 = 0$$
. Hence $(m+2)^2 = 0$

so m = -2 is a repeated root. Hence the general solution is

$$y = (A + Bx)e^{-2x}$$

for arbitrary constants A and B.

3.12.5 Example

Solve the ODE y'' - 2y' + 5y = 0.

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Solve the ODE y'' - 2y' + 5y = 0. **Solution**: Seeking a solution of the form $y = Ae^{mx}$ gives that *m* satisfies the auxiliary equation

$$m^2 - 2m + 5 = 0.$$

This cannot be factorised and so we solve it by formula to get m = 1 + 2i and m = 1 - 2i as the roots. Hence the general solution is

$$y = e^x (A\cos 2x + B\sin 2x)$$

where A and B are arbitrary constants.