# G12MAN Mathematical Analysis: Chapters 1-11

Professor J K Langley

September 25, 2014

Professor J K Langley G12MAN Mathematical Analysis: Chapters 1-11

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▶ Module lecturer: Prof. J K Langley

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- For office hours, optional booklist etc. see the Moodle page. The main teaching resource for this module is these notes and there is no book which is strongly recommended.
- Lectures: see Moodle page
- Problem classes: these will be roughly fortnightly. There will also be some group tutorials. Participation in all of these is vital in order to absorb and master the concepts involved. There will also be opportunities to hand in non-assessed coursework in order to gain practice and feedback. Details will appear on the Moodle page.

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Broad summary: This is a highly theoretical module, with a strong emphasis on proof.

The module is much more about *ideas and concepts* than techniques. It follows on from G11ACF in the first year, so you need to be familiar with the material there.

G12MAN is an introduction to real analysis, mainly featuring the following:

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- ▶ (a) properties of functions on the real line R (in particular involving limits, continuity, differentiation and integration);
- (b) properties of sets in higher dimensional space  $\mathbb{R}^d$ ;
- ▶ (c) properties of functions on subsets of ℝ<sup>d</sup> (such as continuity).

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- There will also be one class test (counting 10%): details will appear on the Moodle page.

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- There will also be one class test (counting 10%): details will appear on the Moodle page.
- If re-assessment is required this will normally be 100% examination (usually in August).

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In the G12MAN examination you will need to be able to state and use the definitions, facts and theorems from the module. While it is unlikely that you would be asked to reproduce the proof of a theorem as given in the slides, the ideas and concepts featuring in the proofs may be required in order to answer questions on the examination. Thus everything in the slides, lectures and problem sets is potentially examinable, except where it is explicitly stated otherwise (e.g. if a topic is marked "optional"). It will also be assumed that you are familiar with material from the Core, in particular G11ACF and G11CAL.

In the examination all answers should be justified fully, supported where appropriate by stating in full facts or theorems from the module. The only exception will be where the question explicitly states that justification is not required. Marks will be lost for careless or disjointed presentation.

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While some marks will be available for stating definitions and/or theorems, to score a good mark on this module you will need to be able to prove statements. The 2012-13 and 2013-14 G12MAN examinations will give you an idea of what to expect, but it is important to note that it takes time and practice to absorb concepts such as those in G12MAN, and merely studying past exam questions is very unlikely to be adequate preparation.

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We will review some of the basic limits from G11ACF, and in particular look at what happens when these are combined.

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Commonly used limits include the following (all in G11ACF).

► The limit of a sequence e.g.

$$\lim_{n \to \infty} \frac{3n+4}{4n+7} = \lim_{n \to \infty} \frac{3+4/n}{4+7/n} = \frac{3+0}{4+0} = \frac{3}{4}$$

(using the algebra of limits from G11ACF).

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The limit of a function e.g. what is

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What happens if we mix these ideas: are the following the same?

(A) 
$$\lim_{n \to +\infty} \left( \lim_{x \to 1-} x^n \right)$$
; (B)  $\lim_{x \to 1-} \left( \lim_{n \to +\infty} x^n \right)$ 

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More commonly used limits:

The derivative of a function e.g. the derivative of f(x) = x<sup>2</sup> at a ∈ ℝ is

$$f'(a) = \lim_{x \to a} \frac{f(x) - f(a)}{x - a} = \lim_{x \to a} \frac{x^2 - a^2}{x - a} = \lim_{x \to a} (x + a) = 2a.$$

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What happens if we combine this concept with that of sequences?

For  $x \in \mathbb{R}$  and  $n \in \mathbb{N} = \{1, 2, \ldots\}$  set

$$f_n(x) = \frac{nx}{1+n^2x^2} \quad , \quad f(x) = \lim_{n \to \infty} f_n(x).$$

Does  $f'_n(0)$  tend to f'(0) as  $n \to \infty$ ?

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Figure 1 shows one of these functions.

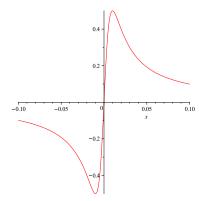


Figure: Plot of the function  $f_{100}$  (MAPLE)

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Commonly used limits include also:

► The sum of a series e.g.

$$T = \sum_{n=1}^{\infty} \left( \frac{1}{n} - \frac{1}{n+1} \right) = \lim_{N \to \infty} \sum_{n=1}^{N} \left( \frac{1}{n} - \frac{1}{n+1} \right).$$

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This gives

$$T = \lim_{N \to \infty} \left( 1 - \frac{1}{2} + \frac{1}{2} - \frac{1}{3} + \dots + \frac{1}{N} - \frac{1}{N+1} \right)$$
$$= \lim_{N \to \infty} \left( 1 - \frac{1}{N+1} \right) = 1.$$

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 If we take infinite sums involving *functions* we can get some very counterintuitive examples.

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▶ Suppose we take  $-\pi < x < \pi$  and look at

$$S(x) = \sum_{n=1}^{\infty} \frac{(-1)^{n+1} \sin nx}{n} = \sin x - \frac{\sin 2x}{2} + \frac{\sin 3x}{3} - \dots$$

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This is an example of a Fourier sine series. These feature in the module G12DEF and are among the most important tools in applied mathematics (waves, temperature distribution etc.).

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▶ Suppose we take  $-\pi < x < \pi$  and look at

$$S(x) = \sum_{n=1}^{\infty} \frac{(-1)^{n+1} \sin nx}{n} = \sin x - \frac{\sin 2x}{2} + \frac{\sin 3x}{3} - \dots$$

- This is an example of a Fourier sine series. These feature in the module G12DEF and are among the most important tools in applied mathematics (waves, temperature distribution etc.).
- ► The sum of the series S(x) for -π < x < π is not obvious! For the determination with proof of the sum you can look at the document

#### **Optional additional material for G12MAN**

on the module Moodle page.

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Figure 2 shows a partial sum.

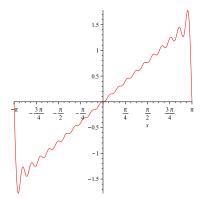


Figure: Plot of the sum of the sine series S(x) up to the n = 20 term (MAPLE)

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But what is important here is whether the following are the same:

(A) 
$$\lim_{x \to \pi^{-}} \left( \sum_{n=1}^{\infty} \frac{(-1)^{n+1} \sin nx}{n} \right) ;$$
  
(B) 
$$\sum_{n=1}^{\infty} \left( \lim_{x \to \pi^{-}} \frac{(-1)^{n+1} \sin nx}{n} \right).$$

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▶ It turns out that in this example the key fact is that the coefficients are  $c_n = (-1)^{n+1}/n$  and

$$\sum_{n=1}^{\infty} |c_n| = 1 + \frac{1}{2} + \frac{1}{3} + \dots$$

diverges (see G11ACF).

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diverges (see G11ACF).

▶ In fact, if  $(a_n)$  is a real sequence such that

$$\sum_{n=1}^{\infty} |a_n|$$

converges, then we always have

$$\lim_{x\to\pi^-}\left(\sum_{n=1}^\infty a_n\sin nx\right)=\sum_{n=1}^\infty a_n\sin n\pi=0.$$

We will see this later in the module, in the section on the Weierstrass *M*-test.

#### ▶ These examples illustrate the need for rigour and proof.

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- Intuition tells you that if you interchange the order of limits you should get the same answer, but the above examples make it clear that this is wrong.

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- ► These examples illustrate the need for rigour and proof.
- Intuition tells you that if you interchange the order of limits you should get the same answer, but the above examples make it clear that this is wrong.
- Analysis gives us tools to determine what does work and why.

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We will review briefly the idea of convergence, and consider the important topic of subsequences.

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 A real sequence (x<sub>n</sub>) just means a non-terminating list of real numbers

 $x_p, x_{p+1}, x_{p+2}, \ldots$ 

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- More precisely, if we are given a permitted error (tolerance)
   ε > 0, then x<sub>n</sub> is within ε of A for for all sufficiently large n.

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- More precisely still, to each positive real number ε corresponds an integer N = N(ε) such that |x<sub>n</sub> − A| < ε for all n ≥ N.</p>

▶ Infinite limits are also possible e.g., as  $n \to \infty$ ,

$$2^n - n^2 \to +\infty, \quad \log \frac{1}{n} \to -\infty.$$

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- ▶ A real sequence  $(x_n)$  is *non-decreasing* for  $n \ge N$  if we have  $x_{n+1} \ge x_n$  for all  $n \ge N$  i.e.

$$x_N \leq x_{N+1} \leq x_{N+2} \leq \ldots$$

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$$x_N \leq x_{N+1} \leq x_{N+2} \leq \dots$$

Saying that (x<sub>n</sub>) is non-increasing just means that (−x<sub>n</sub>) is non-decreasing: equivalently x<sub>n+1</sub> ≤ x<sub>n</sub> for all n ≥ N.

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- If (x<sub>n</sub>) is non-decreasing for n ≥ N then (x<sub>n</sub>) either tends to +∞ or converges;

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- For example

$$X_n = 1 + \frac{1}{4} + \frac{1}{9} + \ldots + \frac{1}{n^2}$$

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In fact X<sub>n</sub> → π<sup>2</sup>/6, which can be shown e.g. using Fourier series (G12DEF).

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An example of a sequence with no limit is

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When we do this we are forming what is called a subsequence.

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$$\frac{1}{2}, \quad \frac{1}{6}, \quad \frac{1}{3}, \quad \frac{1}{8}, \dots$$

is not (why not?).

Now let's take any real sequence  $(x_n)$  (n = p, p + 1, ...).

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Case I: suppose first that every one of these sets E<sub>q</sub> has a maximum element

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• Clearly, if  $p \le q < Q$  then  $E_Q \subseteq E_q$  and so the maximum element of  $E_Q$  is not greater than the maximum element of  $E_q$ .

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Repeating this gives us a non-increasing subsequence x<sub>nk</sub> (k = 1, 2, ...) of (x<sub>n</sub>).

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- Repeating this gives us a non-increasing subsequence x<sub>nk</sub> (k = 1, 2, ...) of (x<sub>n</sub>).
- ► To be precise, once we have chosen n<sub>k</sub>, we choose n<sub>k+1</sub> so that x<sub>n<sub>k+1</sub></sub> is the maximum element of E<sub>1+n<sub>k</sub></sub>.

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- Next, we can find a member of  $E_q$  which is greater than all of

$$x_q = x_{n_1}, \quad x_{1+n_1}, \ldots, \quad x_{n_2}.$$

Let this element be  $x_{n_3}$ : then we must have  $n_3 > n_2$ .

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- Later in the module we will use it in results about the maximum of a function or the intersection of sets.
- For example, the sequence  $\sin n$  (n = 1, 2, ...) goes (2 d.p.)

 $0.84, 0.91, 0.14, -0.75, -0.95, -0.28, 0.66, 0.99, \ldots$ 

and looks quite random, but even this has a convergent subsequence.

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## 3.2 Another look at sequences in $\ensuremath{\mathbb{R}}$

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and looks quite random, but even this has a convergent subsequence.

Which real numbers are the limit of a subsequence of (sin n)? See Optional additional material for G12MAN for answer. This chapter will look at the standard properties of distance in  $\mathbb{R}^d$ , which will later be used in connection with sequences and functions.

$$|x| = \sqrt{x^2} = \begin{cases} x, & \text{if } x \ge 0; \\ -x, & \text{otherwise.} \end{cases}$$

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- ▶ The distance from  $x \in \mathbb{R}$  to  $y \in \mathbb{R}$  equals the distance from x y to 0 and is |x y|.
- This generalises naturally to higher dimensions.

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Figure 3 shows a simple example in  $\mathbb{R}^2$ .

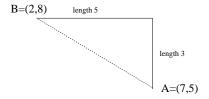


Figure: Straight line between two points

The Euclidean "as the crow flies" distance from A to B is obviously  $\sqrt{3^2 + 5^2} = \sqrt{34} \approx 5.83$ . If we can travel only horizontally and vertically we get  $3 + 5 = 8 > \sqrt{34}$  (sometimes called the "taxicab distance").

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• We will consider points  $\mathbf{x}$  in  $\mathbb{R}^d$  given by

 $\mathbf{x} = (x_1, \ldots, x_d).$ 

Here the coordinates  $x_j$  are real numbers.

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The analogue of the modulus for x is the norm (or length)

$$\|\mathbf{x}\| = \sqrt{x_1^2 + x_2^2 + \ldots + x_d^2} = \sqrt{\sum_{j=1}^d x_j^2}.$$

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It is easy to see that, for each k,

$$\begin{array}{rcl} x_k^2 & \leq & x_1^2 + x_2^2 + \ldots + x_d^2 = |x_1|^2 + |x_2|^2 + \ldots + |x_d|^2 \\ & \leq & (|x_1| + |x_2| + \ldots + |x_d|)^2. \end{array}$$

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• Taking square roots now gives a useful inequality: for each k,

$$|x_k| \leq \|\mathbf{x}\| \leq \sum_{j=1}^d |x_j|.$$

▶ Now suppose we take two points in  $\mathbb{R}^d$  given by

$$\mathbf{x} = (x_1, \dots, x_d), \quad \mathbf{y} = (y_1, \dots, y_d).$$

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• We just define the distance from **x** to **y** (points in  $\mathbb{R}^d$ ) to be

$$ext{dist}\{\mathbf{x},\mathbf{y}\} = \|\mathbf{x}-\mathbf{y}\| = \sqrt{\sum_{j=1}^d (x_j - y_j)^2}.$$

This is the same as the distance from  $\mathbf{0}$  to  $\mathbf{x} - \mathbf{y}$ .

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We then have

$$\|\mathbf{x} - \mathbf{y}\| \leq \sum_{j=1}^d |x_j - y_j|$$

i.e. the distance from  $\mathbf{x}$  to  $\mathbf{y}$  is not greater than the taxicab distance.

▶ A fundamental inequality is the *triangle inequality* for  $\mathbb{R}^d$ :

 $\|\mathbf{x} + \mathbf{y}\| \le \|\mathbf{x}\| + \|\mathbf{y}\|.$ 

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In R<sup>2</sup> or R<sup>3</sup> this is easy to visualise by drawing a parallelogram.
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A useful companion inequality is given by

$$\begin{aligned} \|\mathbf{x}\| &= \|\mathbf{y} + (\mathbf{x} - \mathbf{y})\| \le \|\mathbf{y}\| + \|\mathbf{x} - \mathbf{y}\|, \\ \|\mathbf{x} - \mathbf{y}\| \ge \|\mathbf{x}\| - \|\mathbf{y}\|. \end{aligned}$$

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This is sometimes called the second triangle inequality.

We can interpret the second triangle inequality

$$\|\mathbf{x} - \mathbf{y}\| \geq \|\mathbf{x}\| - \|\mathbf{y}\|$$

as saying that the distance from  ${\bf x}$  to  ${\bf y}$  is at least the distance from  ${\bf x}$  to  ${\bf 0}$  minus the distance from  ${\bf y}$  to  ${\bf 0}.$ 

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# This chapter will look at sequences $(\mathbf{x}_n)$ in which each $\mathbf{x}_n$ is a point in $\mathbb{R}^d$ .

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▶ By a sequence  $(\mathbf{x}_n)$  in  $\mathbb{R}^d$  we mean a non-terminating list

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• We sometimes write  $(\mathbf{x}_n)$  in terms of its coordinates as

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Each coordinate  $x_{n,j}$  then forms a real sequence (j = 1, ..., d). For example, what happens as  $n \to \infty$  for  $(\mathbf{x}_n)$  as follows?

$$\mathbf{x}_n = \left(\frac{\ln n}{\sqrt{n}}, n^{1/n}\right).$$

Suppose we take a sequence (x<sub>n</sub>) and a point a in ℝ<sup>d</sup>. Our basic inequality for points in ℝ<sup>d</sup> gives, for each k,

$$|x_{n,k}-a_k| \leq \|\mathbf{x}_n-\mathbf{a}\| \leq \sum_{j=1}^d |x_{n,j}-a_j|$$

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- This will lead to an important theorem for sequences in  $\mathbb{R}^d$ .

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- We can think of this as discarding some members of the sequence to leave a convergent sequence e.g. for y<sub>n</sub> = (−1)<sup>n</sup> we can discard the even n to leave −1, −1, −1, .....

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- This sequence y<sub>n</sub> is still bounded (the same M will do) so we take another subsequence so that the second coordinate converges.

Keep repeating this. After d steps we get a convergent subsequence of  $(\mathbf{x}_n)$ .

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• Now if we take n = 5, 10, 15, 20, ... in  $y_n$  we get

$$\mathbf{y}_{5k} = \mathbf{x}_{10k} = (1, \cos(k2\pi)) = (1, 1),$$

a convergent subsequence.

Sequences in R<sup>d</sup> aren't in themselves very important, because as we have seen they can be reduced to real sequences by looking at the coordinates.

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- Sequences in R<sup>d</sup> aren't in themselves very important, because as we have seen they can be reduced to real sequences by looking at the coordinates.
- ► However, they are extremely useful when we look at properties of sets in ℝ<sup>d</sup>.

▶ In this chapter we classify in various ways subsets of  $\mathbb{R}^d$ .

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There are also multidimensional "intervals" e.g.

$$G = \{(u, v, w) : 1 < u < 2, 3 \le v < 7, -\pi \le w \le \pi\} \subseteq \mathbb{R}^3.$$

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 x ∈ ℝ<sup>d</sup> and radius r > 0 given by

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This consists of all y whose distance from x is less than r: hence the name ball. The label open will be explained later.

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▶ For example, what is  $H^c$  in  $\mathbb{R}^2$ ?

Given a set E ⊆ ℝ<sup>d</sup>, we look at its *frontier*. An alternative name is *boundary*, but I will use frontier to avoid confusion with a set being "bounded".

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For example the frontier of the open ball (disc) in  $\mathbb{R}^2$  given by

$$E = B(\mathbf{0}, 1) = \{\mathbf{x} \in \mathbb{R}^2 : \|\mathbf{x}\| < 1\} = \{(u, v) : u^2 + v^2 < 1\}$$

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Notice that

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seems to have the same frontier C, and so does

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So **y** is the limit of a sequence in E, and of a sequence in  $E^c$ .

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► We will generally leave out the phrase "with respect to ℝ<sup>d</sup>", since it will be clear which dimension we are working in from the set *E*.

The frontier is also commonly called the "boundary".

This concept can give surprising results, however: what is the frontier of  $\mathbb{Q} \subseteq \mathbb{R}$ ?

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Having defined the frontier of a set, we now consider points which lie in a set but not on its frontier.

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▶ Then for each  $n \in \mathbb{N}$  there exists  $\mathbf{y}_n \in B(\mathbf{x}, 1/n) \cap E$  i.e. there exists  $\mathbf{y}_n \in E$  with  $\|\mathbf{y}_n - \mathbf{x}\| < 1/n$ .

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▶ Then for each  $n \in \mathbb{N}$  there exists  $\mathbf{y}_n \in B(\mathbf{x}, 1/n) \cap E$  i.e. there exists  $\mathbf{y}_n \in E$  with  $\|\mathbf{y}_n - \mathbf{x}\| < 1/n$ .

Suppose next that, for some real r > 0, the open ball B(x, r) does not meet E i.e. B(x, r) ∩ E = Ø.

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- Suppose next that, for some real r > 0, the open ball B(x, r) does not meet E i.e. B(x, r) ∩ E = Ø.
- ► Then there cannot exist a sequence (y<sub>n</sub>) in E with limit x; if we had such a sequence then we would get, for all sufficiently large n,

$$\|\mathbf{y}_n - \mathbf{x}\| < r$$
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• We combine these observations as a useful lemma.

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 Lemma 7.1: Let E be a subset of R<sup>d</sup>, and let x ∈ R<sup>d</sup>. Then the following are equivalent:

 (A) for every real r > 0, the open ball B(x, r) meets E;
 (B) there exists a sequence in E with limit x.

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- ▶ Lemma 7.1: Let E be a subset of R<sup>d</sup>, and let x ∈ R<sup>d</sup>. Then the following are equivalent:
  (A) for every real r > 0, the open ball B(x, r) meets E;
  (B) there exists a sequence in E with limit x.
- Stated another way (using the contrapositive), the following are equivalent:

(C) there exists a real r > 0 such that the open ball  $B(\mathbf{x}, r)$  does not meet E;

(D) there is no sequence in E with limit  $\mathbf{x}$ .

Let A be a subset of ℝ<sup>d</sup>. We define the *interior points* of A as follows. A point x ∈ ℝ<sup>d</sup> is an interior point of A if there exists a real r > 0 such that B(x, r) ⊆ A.

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- Lemma 7.1A: Let A be a subset of R<sup>d</sup>, and let x ∈ R<sup>d</sup>. Then the following are equivalent:
  (i) x is an interior point of A;
  (i') there exists an open ball B(x, r) which does not meet A<sup>c</sup>;
  (ii) there exists no sequence in A<sup>c</sup> with limit x.

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- Thus an interior point of A cannot belong to the frontier  $\partial A$ .
- On the other hand, if y ∈ A is not an interior point of A, then there exists a sequence in A<sup>c</sup> with limit y, so y is in the frontier ∂A. This yields:

## 7.2 Interior points of sets in $\mathbb{R}^d$

**Lemma 7.2:** Let A be any subset of  $\mathbb{R}^d$ . Then

$$A = (int A) \cup (\partial A \cap A),$$

where int A denotes the set of interior points of A, and the two sets int A and  $\partial A \cap A$  are disjoint.

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This says that every point in A is either an interior point or a frontier point, but is never both. **Lemma 7.2:** Let A be any subset of  $\mathbb{R}^d$ . Then

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- Some people refer to ∂A ∩ A as the set of non-interior points in A (sometimes written nint A), but I will not use this terminology.
- ► This leads to an important class of sets, called *open sets*.

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We look at open subsets of  $\mathbb{R}^d$ , which play an important role in analysis.

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# 8.1 Open sets in $\mathbb{R}^d$

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- This is equivalent to the condition that ∂A ∩ A = Ø, which is the same as the condition that ∂A ⊆ A<sup>c</sup> = ℝ<sup>d</sup> \ A.
- The name open will be justified to some extent when we meet closed sets.

Imagine also that you own a field, but none of its boundary edge. Can you prevent your neighbour(s) from stepping on your property?

► For example,

$$H = \{(u, v) \in \mathbb{R}^2 : u > 0\}$$

is an open set. If I take  $\mathbf{x} = (u, v) \in H$ , then in fact  $B(\mathbf{x}, u) \subseteq H$ .

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- $\blacktriangleright$  For  $\mathbf{x} \in \mathbb{R}^d$  the open ball

$$B(\mathbf{x}, r) = \{\mathbf{y} \in \mathbb{R}^d : \|\mathbf{y} - \mathbf{x}\| < r\}$$

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▶ In fact, if  $\|\mathbf{y} - \mathbf{x}\| = s < r$  and  $\mathbf{z} \in \mathbb{R}^d$  then

$$\|\mathbf{z} - \mathbf{y}\| < r - s \Rightarrow \|\mathbf{z} - \mathbf{x}\| \le \|\mathbf{z} - \mathbf{y}\| + \|\mathbf{y} - \mathbf{x}\| < (r - s) + s = r$$

so  $B(\mathbf{y}, r - s) \subseteq B(\mathbf{x}, r)$  (draw a sketch!).

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Alternatively, it's not hard to work out what  $\partial B(\mathbf{x}, r)$  is.

Which of the following sets are open subsets of the given space?

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- Which of the following sets are open subsets of the given space?
- We take

$$(a,b] \subseteq \mathbb{R}; \quad \mathbb{Q} \subseteq \mathbb{R}; \quad \{\mathbf{x} = (u,v) \in \mathbb{R}^2 : \|\mathbf{x}\| \le 1, u > 0\}.$$

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Is the union/intersection of open sets open?

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- Suppose we take the union of some open sets. Do we get an open set?

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- ► To be precise, suppose that U<sub>t</sub> is an open subset of ℝ<sup>d</sup>, for every t belonging to some set T.
- We then look at

$$W = \bigcup_{t \in \mathcal{T}} U_t = \{ \mathbf{x} \in \mathbb{R}^d : \mathbf{x} \text{ is in at least one of the } U_t \}.$$

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Is W open? This will be true if and only if every x ∈ W is an interior point of W, i.e. to each x ∈ W corresponds r > 0 with B(x, r) ⊆ W.

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- ▶ But if we take  $\mathbf{x} \in W$ , then  $\mathbf{x}$  lies in one of the  $U_t$ , and because  $U_t$  is open we get r > 0 with  $B(\mathbf{x}, r) \subseteq U_t$ .

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- Thus W is open:

**Theorem 8.1:** the union of any family of open subsets of  $\mathbb{R}^d$  is an open subset of  $\mathbb{R}^d$ .

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- ► Thus W is open:
   Theorem 8.1: the union of any family of open subsets of ℝ<sup>d</sup> is an open subset of ℝ<sup>d</sup>.
- Notice that we did not use the frontier here, and the frontier of a union may be tricky to determine.

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- But the intersection ∩<sub>n∈ℕ</sub> U<sub>n</sub> of all the U<sub>n</sub> is just {0}, and this is not an open set.
- So the intersection of infinitely many open sets may fail to be open.

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▶ But now let's take *finitely many* open sets, say  $V_1, \ldots, V_n$  (in  $\mathbb{R}^d$ ) and look at their intersection

$$W = \bigcap_{j=1}^n V_j = \{ \mathbf{x} \in \mathbb{R}^d : \mathbf{x} \text{ is in all of the } V_j \}.$$

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- ▶ If I now let r be the minimum of the  $r_j$  then r > 0 and  $B(\mathbf{x}, r) \subseteq B(\mathbf{x}, r_j) \subseteq V_j$  for j = 1, ..., n, and so  $B(\mathbf{x}, r) \subseteq W$ .

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- ► Theorem 8.2: the intersection of finitely many open subsets of ℝ<sup>d</sup> is an open subset of ℝ<sup>d</sup>.

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- ► Theorem 8.2: the intersection of finitely many open subsets of ℝ<sup>d</sup> is an open subset of ℝ<sup>d</sup>.
- You can see from the proof why this fails for infinitely many V<sub>j</sub>: an infinite set of positive real numbers is not guaranteed to have a positive lower bound.

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Closed subsets of  $\mathbb{R}^d$  are again very important from the point of view of analysis.

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▶ First, *closed* does not mean "not open"!

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- ▶ First, *closed* does not mean "not open"!
- ▶ A set  $A \subseteq \mathbb{R}^d$  is called closed if  $B = A^c = \mathbb{R}^d \setminus A$  is open.

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- ▶ A set  $A \subseteq \mathbb{R}^d$  is called closed if  $B = A^c = \mathbb{R}^d \setminus A$  is open.
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- Since ∂A = ∂B, this is equivalent to the condition that B ∩ ∂A = Ø, and so equivalent to the condition that ∂A ⊆ A.
- Closed sets can be characterised in terms of sequences.

# Let A be a subset of ℝ<sup>d</sup>. Then the following are equivalent. A is not closed.

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- A is not closed.
- $B = A^c = \mathbb{R}^d \setminus A$  is not open.
- There exists  $\mathbf{x} \in B$  which is not an interior point of B.

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- ► There exists x ∈ B and a sequence in B<sup>c</sup> = A with limit x (using Lemma 7.1A).
- There exists a convergent sequence in A whose limit is not in A.

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Taking contrapositives we get:

**Theorem 9.1:** Let A be a subset of  $\mathbb{R}^d$ . Then A is closed if and only if every convergent sequence  $(\mathbf{x}_n)$  in A satisfies  $\lim_{n\to\infty} \mathbf{x}_n \in A$ . So a closed set A is closed in the sense that a convergent sequence in A cannot escape to a limit outside A.

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Let A be a subset of ℝ<sup>d</sup>. We say that A is bounded if there exists a positive real number M such that ||x|| < M for every x ∈ A i.e. A ⊆ B(0, M).</p>

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- Suppose that A is closed and bounded, and take a sequence (x<sub>n</sub>) in A.
- ► Then (x<sub>n</sub>) is a bounded sequence and so has a convergent subsequence (Bolzano-Weierstrass).

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- Suppose that A is closed and bounded, and take a sequence (x<sub>n</sub>) in A.
- ► Then (x<sub>n</sub>) is a bounded sequence and so has a convergent subsequence (Bolzano-Weierstrass).
- Because A is closed the convergent subsequence must have limit in A.

 Suppose on the other hand that A is not closed. Then by Theorem 9.1 there exists a convergent sequence (x<sub>n</sub>) in A with y = lim<sub>n→∞</sub> x<sub>n</sub> not in A. Here any subsequence of (x<sub>n</sub>) must also have limit y ∉ A.

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- What happens if A is not bounded? Then we can find y<sub>n</sub> ∈ A with ||y<sub>n</sub>|| > n → ∞, and this sequence cannot have a convergent subsequence.

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- What happens if A is not bounded? Then we can find y<sub>n</sub> ∈ A with ||y<sub>n</sub>|| > n → ∞, and this sequence cannot have a convergent subsequence.
- Combining these, we get another important theorem.

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**Theorem 9.2:** Let A be a subset of  $\mathbb{R}^d$ . Then the following are equivalent:

(i) The set A is closed and bounded.

(ii) Every sequence in A has a convergent subsequence with limit in A.

This is sometimes called the *Heine-Borel theorem*.

A set A which satisfies condition (ii) is called sequentially compact.

Suppose that E<sub>1</sub>, E<sub>2</sub>,... are non-empty closed and bounded subsets of ℝ<sup>d</sup>, with

 $E_1 \supseteq E_2 \supseteq E_3 \supseteq \ldots$ 

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► Take x<sub>j</sub> ∈ E<sub>j</sub>. Then (x<sub>n</sub>) is a sequence in the closed and bounded set E<sub>1</sub>.

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- ▶ Then  $(\mathbf{x}_n)$  has a convergent subsequence (say  $(\mathbf{x}_{n_k})$ , with  $1 \le n_1 < n_2 < \ldots$ ). Let  $\mathbf{a} = \lim_{k\to\infty} \mathbf{x}_{n_k}$ .

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- ▶ Now take  $m \in \mathbb{N}$ . Since  $n_k \ge m$  for all  $k \ge m$  we have  $\mathbf{x}_{n_k} \in E_m$  for all  $k \ge m$ .

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- ▶ Now take  $m \in \mathbb{N}$ . Since  $n_k \ge m$  for all  $k \ge m$  we have  $\mathbf{x}_{n_k} \in E_m$  for all  $k \ge m$ .
- Hence  $\mathbf{a} \in E_m$ , since  $E_m$  is closed, and so

$$\mathbf{a} \in \bigcap_{j=1}^{\infty} E_j$$

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Theorem 9.3 (nested closed and bounded sets theorem) Suppose that E<sub>1</sub>, E<sub>2</sub>,... are non-empty closed and bounded subsets of R<sup>d</sup>, with

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Then the intersection

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Is this still true if we drop the word "closed"?

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- Is this still true if we drop the word "closed"?
- Is this still true if we drop the word "bounded"?

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We will consider continuous functions defined on (subsets of)  $\mathbb{R}^d$  and their properties.

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▶ If we have a function  $f : \mathbb{R} \to \mathbb{R}$  then f is continuous at  $a \in \mathbb{R}$  if

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- More precisely, given any positive real number ε, there exists a positive real number δ such that |f(x) − f(a)| < ε for all x with |x − a| < δ.</p>
- Here ε can be thought of as εrror, or tolεrance, and δ as δisplacement, or δistance.

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We will extend this first to functions defined on an open set U ⊆ ℝ<sup>d</sup>.

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- An open set U has the advantage that if a ∈ U then all points
   x which are sufficiently close to a also lie in U.
- Later we will consider functions on any  $E \subseteq \mathbb{R}^d$ .

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So suppose we have a function  $\mathbf{f} : U \to \mathbb{R}^q$ , where  $U \subseteq \mathbb{R}^d$  is open.

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- Again this just says that the distance from f(x) to f(a) is as small as we like, provided the distance from x to a is small enough.

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- Again this just says that the distance from f(x) to f(a) is as small as we like, provided the distance from x to a is small enough.
- ▶ Keep in mind, though, that the first distance ||f(x) f(a)|| is with respect to ℝ<sup>q</sup>, and the second distance ||x a|| is with respect to ℝ<sup>d</sup>.

▶ We can express this idea in terms of sequences. Suppose we have a function  $\mathbf{f} : U \to \mathbb{R}^q$ , where  $U \subseteq \mathbb{R}^d$  is open.

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- Since  $(\mathbf{x}_n)$  converges to **a** there exists an integer N such that  $\|\mathbf{x}_n \mathbf{a}\| < \delta$  for all  $n \ge N$ .

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- This gives  $\|\mathbf{f}(\mathbf{x}_n) \mathbf{f}(\mathbf{a})\| < \varepsilon$  for all  $n \ge N$ .
- Since we can do this for any ε > 0, we conclude that f(x<sub>n</sub>) converges to f(a).

➤ On the other hand, suppose that f is NOT continuous at a ∈ U.

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- Then there must exist a positive real number ε having NO positive real number δ such that ||f(x) − f(a)|| < ε for all x with ||x − a|| < δ.</p>

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- ▶ So for each  $n \in \mathbb{N}$  we can find  $\mathbf{x}_n$  with  $\|\mathbf{x}_n \mathbf{a}\| < 1/n$  but  $\|\mathbf{f}(\mathbf{x}_n) \mathbf{f}(\mathbf{a})\| \ge \varepsilon$ .

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- So  $(\mathbf{x}_n)$  converges to  $\mathbf{a}$ , but  $(\mathbf{f}(\mathbf{x}_n))$  does not converge to  $\mathbf{f}(\mathbf{a})$ .

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- Combining this reasoning gives the following theorem.

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**Theorem 10.1:** Let  $\mathbf{f} : U \to \mathbb{R}^q$  be a function, where  $U \subseteq \mathbb{R}^d$  is open, and let  $\mathbf{a} \in U$ . Then the following are equivalent: (i)  $\mathbf{f}$  is continuous at  $\mathbf{a}$ ; (ii) for every sequence  $(\mathbf{x}_n)$  in  $\mathbb{R}^d$  which converges to  $\mathbf{a}$ , the image sequence  $(\mathbf{f}(\mathbf{x}_n))$  converges to  $\mathbf{f}(\mathbf{a})$ .

Suppose next that we write our function  $\mathbf{f} : U \to \mathbb{R}^q$  in terms of its coordinates as

$$\mathbf{f}=(f_1,\ldots,f_q),$$

and suppose we take a sequence  $(\mathbf{x}_n)$  in  $\mathbb{R}^d$ .

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▶ Then from Chapter 5 we know that  $(\mathbf{f}(\mathbf{x}_n))$  converges to  $\mathbf{f}(\mathbf{a})$  if and only if each coordinate sequence  $(f_j(\mathbf{x}_n))$  converges to  $f_j(\mathbf{a})$ .

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- ► Then from Chapter 5 we know that (f(x<sub>n</sub>)) converges to f(a) if and only if each coordinate sequence (f<sub>j</sub>(x<sub>n</sub>)) converges to f<sub>j</sub>(a).
- So **f** is continuous at **a** if and only if all the  $f_j$  are.

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- So **f** is continuous at **a** if and only if all the *f<sub>i</sub>* are.
- So the continuity of our function f = (f<sub>1</sub>,..., f<sub>q</sub>) is equivalent to the continuity of all of its coordinate functions f<sub>i</sub>.

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Now consider

$$f(u,v) = \frac{u^4 v^2}{u^8 + v^4}$$
 (if  $(u,v) \neq (0,0)$ ),  $f(0,0) = 0$ .

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• If we fix v = 0 then we get

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• Similarly, if we fix u = 0 we get

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So if we fix one variable (u or v) and regard f as a function of the other variable then f is continuous.

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- So if we fix one variable (u or v) and regard f as a function of the other variable then f is continuous.
- But is f really continuous as a function of both variables?

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If we let (u, v) → (0,0) along a straight line u = mv (where m is a non-zero constant) then we get

$$f(mv,v) = rac{m^4 v^6}{m^8 v^8 + v^4} = rac{m^4 v^2}{m^8 v^4 + 1} o 0$$
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$$(u, v) \rightarrow (0, 0)$$
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▶ So as  $(u, v) \rightarrow (0, 0)$  along any straight line we have  $f(u, v) \rightarrow 0$ .

▶ But if we let  $(u, v) \rightarrow (0, 0)$  along the curve  $v = u^2$  we get

$$f(u,v) = f(u,u^2) = \frac{u^4 u^4}{u^8 + u^8} = \frac{1}{2} \rightarrow \frac{1}{2} \neq f(0,0).$$

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$$f(u,v) = f(u,u^2) = \frac{u^4 u^4}{u^8 + u^8} = \frac{1}{2} \to \frac{1}{2} \neq f(0,0).$$

▶ So *f* is NOT continuous at (0,0).

The conclusion is that in deciding whether a function f = (f<sub>1</sub>,..., f<sub>q</sub>) is continuous it is sufficient to look at each coordinate f<sub>j</sub> of the image separately, but it is NOT sufficient to consider f with respect to each coordinate variable x<sub>k</sub> separately.

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- Nor is it enough to look at f as x approaches a point along straight lines.
- In general it can be quite tricky to determine whether a function of several variables is continuous, but the next example shows how this can be done in some cases.

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We change 
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 to  $v^3$  in the numerator to get  

$$g(u, v) = \frac{u^4 v^3}{u^8 + v^4} \quad (\text{if } (u, v) \neq (0, 0)), \quad g(0, 0) = 0.$$

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- If you try this method on the previous example you will see that it is inconclusive.

So far we have only defined continuity for functions defined on open sets in ℝ<sup>d</sup>.

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When E is open this is, by Theorem 10.1, equivalent to f being continuous, in terms of the original definition, at every point in E.

An important case is where E is a closed and bounded subset of ℝ<sup>d</sup>. Let E ⊆ ℝ<sup>d</sup> be closed and bounded, and let
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- The theorem tells us that f is bounded on E. Does f have a maximum on E?

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- Since *M* is the *least* upper bound there are members of *A* as close as we like to *M*, and so we can find x ∈ *E* with *f*(x) as close as we like to *M*.
- So there must be some x ∈ E with f(x) = M, because if not then the function

$$g(\mathbf{x}) = \frac{1}{M - f(\mathbf{x})}$$

is continuous, real-valued and unbounded on the closed and bounded set E, contradicting the fact that g(E) must be closed and bounded.

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#### We deduce:

**Theorem 10.3 (the maximum theorem for continuous functions):** Let  $E \subseteq \mathbb{R}^d$  be closed and bounded and non-empty, and let  $f : E \to \mathbb{R}$  be a continuous real-valued function on E. Then f has a maximum on E i.e. there exists  $\mathbf{x}_0 \in E$  with  $f(\mathbf{x}) \leq f(\mathbf{x}_0)$  for every  $\mathbf{x} \in E$ .

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- Note that  $x_0$  does not have to be unique here.
- ► Applying the theorem to -f, we also get that f has a minimum on E.
- The particular case where E = [a, b] is a closed and bounded interval in ℝ is one of the most important theorems in calculus.

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We are not assuming here that f is injective or has an inverse function: the notation f<sup>-1</sup>(V) just means all points which are mapped into V. Suppose first that **f** is continuous, and take  $\mathbf{x}_0 \in \mathbf{f}^{-1}(V)$ .

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- This tells us that  $\mathbf{f}^{-1}(V)$  is open.

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Conversely, suppose we know that f<sup>-1</sup>(V) is open, for every open subset V of ℝ<sup>q</sup>.

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- Since  $\mathbf{x}_0 \in \mathbf{f}^{-1}(V)$ , we get  $\delta > 0$  such that  $B(\mathbf{x}_0, \delta) \subseteq \mathbf{f}^{-1}(V)$ .
- This tells us that ||x − x<sub>0</sub>|| < δ implies ||f(x) − f(x<sub>0</sub>)|| < ε, and since we can do this for any ε > 0 our f must be continuous.

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### We deduce:

**Theorem 10.4:** Let  $\mathbf{f} : \mathbb{R}^d \to \mathbb{R}^q$  be a function. Then the following are equivalent: (a)  $\mathbf{f}$  is continuous on  $\mathbb{R}^d$ ;

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- ► There is a version of this for functions on subsets of ℝ<sup>d</sup>, but it is not quite so easy to state.
- This idea gives a useful alternative approach to continuity (avoiding ε and δ) and this is developed in the module G13MTS (Metric and Topological Spaces).

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We saw in Chapter 2 that taking sequences of functions may lead to unexpected consequences. This chapter will introduce a strong form of convergence called *uniform* convergence.

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• We start with an example. For  $n \in \mathbb{N}$  and  $x \in [0, 1] \subseteq \mathbb{R}$  set  $f_n(x) = x^n$ .

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- We saw similar phenomena in Chapter 2.

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The problem is that the condition

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(which is usually called pointwise convergence) is not generally strong enough for the limit f to inherit "nice" properties (such as being continuous) from the  $f_n$ .

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We will define a stronger form of convergence of functions, which does preserve many good properties.

 Let E ⊆ ℝ<sup>d</sup> and let f<sub>n</sub> (n = p, p + 1,...) and f be functions from E into ℝ<sup>q</sup>. We say that f<sub>n</sub> converges uniformly to f on E if

 $\sup\{\|\mathbf{f}_n(\mathbf{x}) - \mathbf{f}(\mathbf{x})\| : \mathbf{x} \in E\} \to 0 \quad \text{as } n \to \infty.$ 

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• If this is true then for each  $\mathbf{y} \in E$  we have

 $\|\mathbf{f}_n(\mathbf{y}) - \mathbf{f}(\mathbf{y})\| \le \sup\{\|\mathbf{f}_n(\mathbf{x}) - \mathbf{f}(\mathbf{x})\| : \mathbf{x} \in E\} \to 0 \quad \text{as } n \to \infty.$ 

Thus uniform convergence on E implies pointwise convergence on E.

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Thus uniform convergence on E implies pointwise convergence on E.

But for our first example

 $\sup\{|f_n(x)-f(x)|: 0 \le x \le 1\} = \sup\{x^n: 0 \le x < 1\} = 1 \not\to 0,$ 

and so in this example the convergence is NOT uniform.

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▶ Let  $E \subseteq \mathbb{R}^d$  and suppose that *continuous* functions  $\mathbf{f}_n : E \to \mathbb{R}^q$  converge uniformly to  $\mathbf{f} : E \to \mathbb{R}^q$  on E.

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- Must f also be continuous on E?
- ▶ It is enough to show that for every convergent sequence  $(\mathbf{x}_m)$  in *E* with limit  $\mathbf{a} \in E$  we have  $\lim_{m\to\infty} \mathbf{f}(\mathbf{x}_m) = \mathbf{f}(\mathbf{a})$ .

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- To do this it is enough to take ε > 0 and find an integer M such that ||f(x<sub>m</sub>) − f(a)|| < ε for all m ≥ M.</p>

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▶ First of all, since  $\mathbf{f}_n \to \mathbf{f}$  uniformly on *E*, we can find  $N \in \mathbb{N}$  such that

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for all  $m \geq M$ .

▶ Now for  $m \ge M$  we use the triangle inequality to write

$$\begin{aligned} \|\mathbf{f}(\mathbf{x}_m) - \mathbf{f}(\mathbf{a})\| &= \|\mathbf{f}(\mathbf{x}_m) - \mathbf{f}_N(\mathbf{x}_m) + \\ &+ \mathbf{f}_N(\mathbf{x}_m) - \mathbf{f}_N(\mathbf{a}) + \mathbf{f}_N(\mathbf{a}) - \mathbf{f}(\mathbf{a})\| \\ &\leq \|\mathbf{f}(\mathbf{x}_m) - \mathbf{f}_N(\mathbf{x}_m)\| + \|\mathbf{f}_N(\mathbf{x}_m) - \mathbf{f}_N(\mathbf{a})\| + \\ &+ \|\mathbf{f}_N(\mathbf{a}) - \mathbf{f}(\mathbf{a})\| \\ &< \varepsilon/3 + \varepsilon/3 + \varepsilon/3 = \varepsilon \end{aligned}$$

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We deduce:

**Theorem 11.1:** Let  $E \subseteq \mathbb{R}^d$  and suppose that the functions  $\mathbf{f}_n : E \to \mathbb{R}^q$  converge uniformly to  $\mathbf{f} : E \to \mathbb{R}^q$  on E. If the  $\mathbf{f}_n$  are continuous on E then so is  $\mathbf{f}$ .

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 Put briefly, the uniform limit of continuous functions is continuous.

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 Let E ⊆ ℝ<sup>d</sup> and suppose that the functions f<sub>k</sub> : E → ℝ<sup>q</sup> satisfy

 $\|\mathbf{f}_k(\mathbf{x})\| \le M_k$  for all  $k \ge p$  and all  $\mathbf{x} \in E$ ,

and suppose that

$$\sum_{k=p}^{\infty} M_k < \infty.$$

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On E we look at the sum

$$\mathbf{F}(\mathbf{x}) = \sum_{k=p}^{\infty} \mathbf{f}_k(\mathbf{x})$$

and the partial sums

$$\mathbf{F}_n(\mathbf{x}) = \sum_{k=p}^n \mathbf{f}_k(\mathbf{x})$$

For  $n \ge p$  and  $\mathbf{x} \in E$  we can write, by the triangle inequality,

$$\begin{aligned} \mathbf{F}(\mathbf{x}) - \mathbf{F}_n(\mathbf{x}) \| &= \lim_{m \to \infty} \|\mathbf{F}_m(\mathbf{x}) - \mathbf{F}_n(\mathbf{x})\| \\ &= \lim_{m \to \infty} \left\| \sum_{k=n+1}^m \mathbf{f}_k(\mathbf{x}) \right\| \\ &\leq \lim_{m \to \infty} \sum_{k=n+1}^m \|\mathbf{f}_k(\mathbf{x})\| \\ &\leq \lim_{m \to \infty} \sum_{k=n+1}^m M_k \\ &= \sum_{k=n+1}^\infty M_k. \end{aligned}$$

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Hence the series F converges uniformly on E, in the sense that the partial sums F<sub>n</sub> converge uniformly to F on E. This is: **Theorem 11.2 (the Weierstrass** *M***-test):** Let  $E \subseteq \mathbb{R}^d$  and suppose that the functions  $\mathbf{f}_k : E \to \mathbb{R}^q$  satisfy

$$\|\mathbf{f}_k(\mathbf{x})\| \le M_k$$
 for all  $k \ge p$  and all  $\mathbf{x} \in E$ ,

where

$$\sum_{k=p}^{\infty} M_k < \infty.$$

Then the series

$$\mathsf{F}(\mathsf{x}) = \sum_{k=p}^{\infty} \mathsf{f}_k(\mathsf{x})$$

converges uniformly on *E*. In particular, if the  $f_k$  are continuous on *E* then so is **F**.

As a special case we can take our example from Chapter 2: if a<sub>n</sub> ∈ ℝ and ∑<sub>n=1</sub><sup>∞</sup> |a<sub>n</sub>| < ∞, look at</p>

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$$U(x)=\sum_{n=1}^{\infty}a_n\sin nx.$$

• What is  $\lim_{x\to\pi^-} U(x)$ ?

• Unfortunately, even uniform convergence has its limitations. For example, as  $n \to \infty$ ,

$$f_n(x) = \frac{\sin(n^2 x)}{n}$$

converges uniformly on  $\mathbb{R}$  to 0 (since  $|f_n(x) - 0| \leq 1/n$  on  $\mathbb{R}$ ).

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But is it true that the derivative of the limit equals the limit of the derivative?

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An important application of the *M*-test is the famous Schoenberg curve.

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- (i)  $\phi$  has period 2 (i.e.  $\phi(t+2) = \phi(t)$ );

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- (ii) we have  $\phi(t) = 0$  for  $0 \le t \le 1/3$ ;
- (iii) we have  $\phi(t) = 1$  for  $2/3 \le t \le 1$ .

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Figure 4 shows the standard way to define the Schoenberg function  $\phi.$ 

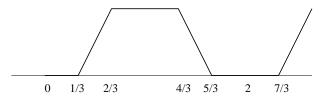


Figure: Part of the graph of the periodic function  $\phi$ 

Now we set

$$f_1(t) = \sum_{n=1}^{\infty} \frac{\phi(3^{2n-2}t)}{2^n}, \quad f_2(t) = \sum_{n=1}^{\infty} \frac{\phi(3^{2n-1}t)}{2^n}.$$

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- Where does this curve lie? We have

$$0 \leq f_j(t) \leq \sum_{n=1}^{\infty} \frac{1}{2^n} = \frac{1}{2} + \frac{1}{4} + \ldots = 1,$$

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How much of this square does it occupy?

► To answer this question take the point (a, b) ∈ [0, 1]<sup>2</sup> with a, b ∈ [0, 1] and write a and b in binary as

$$a = \frac{a_1}{2} + \frac{a_2}{4} + \frac{a_3}{8} + \dots, \quad b = \frac{b_1}{2} + \frac{b_2}{4} + \frac{b_3}{8} + \dots,$$

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$$c = 2\left(\frac{a_1}{3} + \frac{b_1}{9} + \frac{a_2}{27} + \frac{b_2}{81} + \ldots\right) = 2\sum_{n=1}^{\infty} \frac{c_n}{3^n}.$$

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• Here  $c_{2n} = b_n$  and  $c_{2n-1} = a_n$  for  $n \in \mathbb{N}$ .

Note that

$$0 \le c \le 2\left(\frac{1}{3} + \frac{1}{9} + \frac{1}{27} + \dots\right) = \frac{2}{3}\left(\frac{1}{1 - 1/3}\right) = 1.$$

• We calculate  $\mathbf{f}(c)$ .

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- We calculate  $\mathbf{f}(c)$ .
- To do this let  $k \ge 0$  be an integer. Then

$$3^{k}c = 2\sum_{n=1}^{\infty} \frac{c_{n}}{3^{n-k}} = 2\sum_{1 \le n \le k} \frac{c_{n}}{3^{n-k}} + 2\sum_{n=k+1}^{\infty} \frac{c_{n}}{3^{n-k}}.$$

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$$2\sum_{1 \le n \le k} \frac{c_n}{3^{n-k}} = 2\sum_{1 \le n \le k} c_n 3^{k-n}$$

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• So since  $\phi$  has period 2 we get that

$$\phi(3^k c) = \phi(d_k), \quad d_k = 2 \sum_{n=k+1}^{\infty} \frac{c_n}{3^{n-k}} = 2 \sum_{m=1}^{\infty} \frac{c_{k+m}}{3^m}.$$

Now  $c_{k+1}$  is either 0 or 1. If  $c_{k+1}$  is 0 then

$$0 \le d_k = 2\sum_{m=1}^{\infty} \frac{c_{k+m}}{3^m} = 2\sum_{m=2}^{\infty} \frac{c_{k+m}}{3^m} \le 2\left(\frac{1}{9} + \frac{1}{27} + \ldots\right) = \frac{1}{3},$$

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• So in either case we have  $\phi(3^k c) = c_{k+1}$ .

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- This means that f(c) is the point (a, b) and so f([0, 1]) occupies the whole unit square [0, 1]<sup>2</sup>.
- So a square can be filled up using a curve, and this highly counter-intuitive fact ends the first half of the module.

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