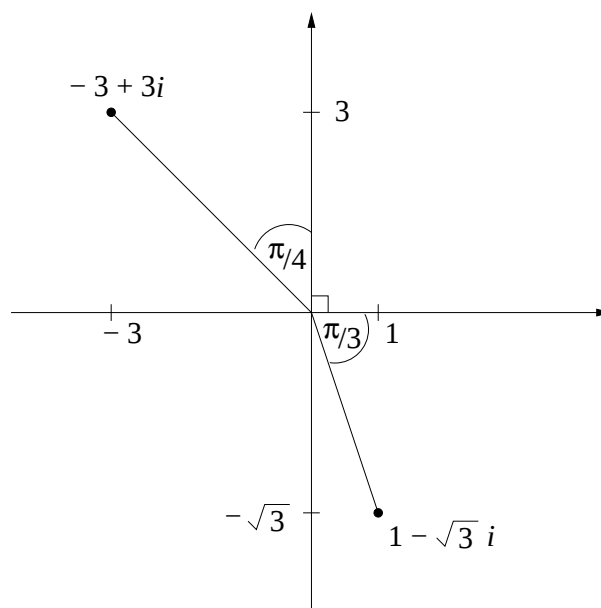


Examination Solutions

1. (a) i. $(2 + 5i)(3 - i) = (6 + 5) + (15 - 2)i = 11 + 13i$. Real part is 11, imaginary part is 13.
- ii. $\frac{2 + 5i}{3 - i} = \frac{(2 + 5i)(3 + i)}{(3 - i)(3 + i)} = \frac{1 + 17i}{10} = \frac{1}{10} + \frac{17}{10}i$ Real part is $\frac{1}{10}$, imaginary part is $\frac{17}{10}$.
- (b)



$$\text{Arg}(-3 + 3i) = \frac{\pi}{2} + \frac{\pi}{4} = \frac{3\pi}{4}$$

$$\text{Arg}(1 - \sqrt{3}i) = -\frac{\pi}{3}$$

$$|-3 + 3i| = \sqrt{3^2 + 3^2} = \sqrt{18} \quad \text{so}$$

$$-3 + 3i = \sqrt{18}e^{i(3\pi/4)}$$

$$|1 - \sqrt{3}i| = \sqrt{1^2 + (\sqrt{3})^2} = \sqrt{4} = 2 \quad \text{so}$$

$$1 - \sqrt{3}i = 2e^{-i\pi/3}.$$

(c)

$$\begin{aligned} (1 - \sqrt{3}i)^9 &= (2e^{-i\pi/3})^9 \\ &= 2^9 e^{-i9\pi/3} \\ &= 2^9 e^{-i3\pi} \\ &= 512 \times (-1) = -512. \end{aligned}$$

2. (a)

$$\|\mathbf{a}\| = \sqrt{2^2 + 1^2 + 4^2} = \sqrt{21}$$

$$\|\mathbf{b}\| = \sqrt{1^2 + 2^2 + 2^2} = \sqrt{9} = 3$$

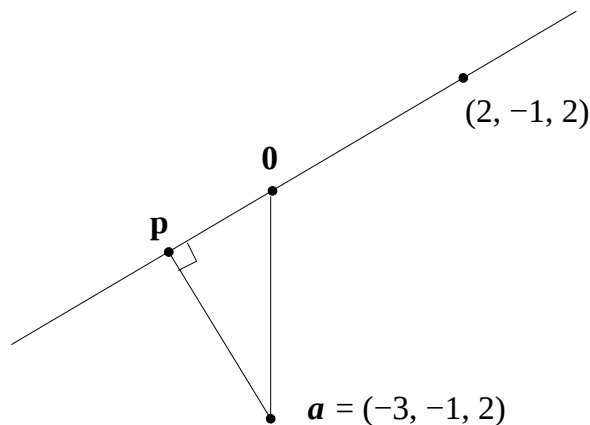
$$\mathbf{a} \cdot \mathbf{b} = 2 \times (-1) + (-1) \times 2 + 4 \times (-2) = -12$$

$$\mathbf{a} \times \mathbf{b} = (2 - 8, -4 + 4, 4 - 1) = (-6, 0, 3).$$

$\mathbf{a} \cdot \mathbf{b} = \|\mathbf{a}\| \|\mathbf{b}\| \cos(\theta)$ gives us

$$\cos(\theta) = \frac{\mathbf{a} \cdot \mathbf{b}}{\|\mathbf{a}\| \|\mathbf{b}\|} = \frac{-12}{3\sqrt{21}} = \frac{-4}{\sqrt{21}}.$$

(b)



$\mathbf{p}$ is the component of $\mathbf{a}$ along $(2, -1, -2)$.

Set $\mathbf{b} = (2, -1, -2)$. So $\mathbf{p} = \frac{(\mathbf{a} \cdot \mathbf{b})}{(\mathbf{b} \cdot \mathbf{b})} \mathbf{b} = \frac{(-6 + 1 - 4)}{9} \mathbf{b} = -\mathbf{b} = (-2, 1, 2)$.

Distance from $\mathbf{a}$ to L is then

$$\|\mathbf{a} - \mathbf{p}\| = \sqrt{1^2 + 2^2 + 0} = \sqrt{5}.$$

3. (a)

$$\begin{bmatrix} 1 & -2 & 0 \\ 2 & 0 & 3 \\ 0 & -2 & 4 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ 5 & 2 \\ 4 & 5 \end{bmatrix} = \begin{bmatrix} 3 - 10 & -2 - 4 \\ 6 + 12 & -4 + 15 \\ -10 + 16 & -4 + 20 \end{bmatrix}$$

$$= \begin{bmatrix} -7 & -6 \\ 18 & 11 \\ 6 & 16 \end{bmatrix}$$

$$\begin{bmatrix} i & 2 \\ 3 & -i \end{bmatrix} \begin{bmatrix} 1+i & -i \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} i - 1 + 4 & 1 + 2 \\ 3 + 3i - 2i & -3i - i \end{bmatrix}$$

$$= \begin{bmatrix} 3 + i & 3 \\ 3 + i & -4i \end{bmatrix}.$$

(b) Using row operations which do not change the value of the determinant,

$$\begin{aligned}
 & \begin{vmatrix} 1 & 2 & -1 & 3 \\ 2 & 6 & -1 & 16 \\ 1 & 6 & 0 & 27 \\ 3 & 10 & -2 & 38 \end{vmatrix} = \begin{matrix} R_2 - 2R_1 \\ R_3 - R_1 \\ R_4 - 3R_1 \end{matrix} \begin{vmatrix} 1 & 2 & -1 & 3 \\ 0 & 2 & 1 & 10 \\ 0 & 4 & 1 & 24 \\ 0 & 4 & 1 & 29 \end{vmatrix} \\
 & = R_4 - R_3 \begin{vmatrix} 1 & 2 & -1 & 3 \\ 0 & 2 & 1 & 10 \\ 0 & 4 & 1 & 24 \\ 0 & 0 & 0 & 5 \end{vmatrix} = R_3 - 2R_2 \begin{vmatrix} 1 & 2 & -1 & 3 \\ 0 & 2 & 1 & 10 \\ 0 & 0 & -1 & 4 \\ 0 & 0 & 0 & 5 \end{vmatrix} \\
 & = 1 \times (2) \times (-1) \times 5 = -10
 \end{aligned}$$

as the last is the determinant of a triangular matrix.

(c) We may take $A = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$, $B = \begin{bmatrix} 0 & 0 \\ 0 & 5 \end{bmatrix}$. Then $\det(A + B) = \det\left(\begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix}\right) = 10$ while $\det(A) = \det(B) = 0$. Thus $\det(A + B) = \det(A) + \det(B) + 10$. as required.

4. (a) We form the augmented matrix and row reduce to echelon form.

$$\begin{aligned}
 & \left[\begin{array}{cccc|c} 1 & -2 & 3 & 1 & 2 \\ 3 & -6 & 11 & 2 & 9 \\ 2 & -4 & 8 & 1 & 7 \end{array} \right] \sim \begin{matrix} R_2 - 3R_1 \\ R_3 - 2R_1 \end{matrix} \left[\begin{array}{cccc|c} 1 & -2 & 3 & 1 & 2 \\ 0 & 0 & 2 & -1 & 3 \\ 0 & 0 & 2 & -1 & 3 \end{array} \right] \\
 & \sim R_3 - R_2 \left[\begin{array}{cccc|c} 1 & -2 & 3 & 1 & 2 \\ 0 & 0 & 2 & -1 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]
 \end{aligned}$$

This is now in echelon form and we can see that the equations are consistent, with leading variables x_1, x_3 and free variables x_2, x_4 .

To find the general solution, set $x_2 = s, x_4 = t$. The second row of the echelon matrix gives $2x_3 - x_4 = 3$ so

$$x_3 = \frac{1}{2}(3 + x_4) = \frac{3}{2} + \frac{t}{2}.$$

The first row gives us

$$\begin{aligned}
 & x_1 - 2x_2 + 3x_3 + x_4 = 2, \quad \text{i.e.} \\
 & x_1 - 2s + 3\left(\frac{3}{2} + \frac{t}{2}\right) + t = 2, \quad \text{giving} \\
 & x_1 = 2s + \left(2 - \frac{9}{2}\right) - \frac{5}{2}t = 2s - \frac{5}{2}t - \frac{5}{2}.
 \end{aligned}$$

The general solution is thus

$$\begin{aligned}
 (x_1, x_2, x_3, x_4) &= \left(2s - \frac{5}{2}t - \frac{5}{2}, s, \frac{3}{2} + \frac{t}{2}, t\right) \\
 &= \left(-\frac{5}{2}, 0, \frac{3}{2}, 0\right) + s(2, 1, 0, 0) + t\left(-\frac{5}{2}, 0, \frac{1}{2}, 1\right).
 \end{aligned}$$

(b) Using Gauss-Jordan inversion

$$\begin{aligned}
& \left[\begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 2 & -1 & 4 & 0 & 1 & 0 \\ 3 & -1 & 7 & 0 & 0 & 1 \end{array} \right] \sim \begin{array}{l} R_2 - 2R_1 \\ R_3 - 3R_1 \end{array} \left[\begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -2 & 1 & 0 \\ 0 & 2 & 1 & -3 & 0 & 1 \end{array} \right] \\
& \sim R_3 - 2R_2 \left[\begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -2 & 1 & 0 \\ 0 & 0 & 1 & 1 & -2 & 1 \end{array} \right] \\
& \sim R_1 + R_2 \left[\begin{array}{ccc|ccc} 1 & 0 & 2 & -1 & 1 & 0 \\ 0 & 1 & 0 & -2 & 1 & 0 \\ 0 & 0 & 1 & 1 & -2 & 1 \end{array} \right] \\
& \sim R_1 - 2R_3 \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -3 & 5 & -2 \\ 0 & 1 & 0 & -2 & 1 & 0 \\ 0 & 0 & 1 & 1 & -2 & 1 \end{array} \right]
\end{aligned}$$

So the inverse to the original matrix is

$$\begin{bmatrix} -3 & 5 & -2 \\ -2 & 1 & 0 \\ 1 & -2 & 1 \end{bmatrix}.$$

(This may also be done using $\det$ and adj.)

The second matrix is quickly inverted using the formula for inverting 2×2 matrices. When $ad - bc \neq 0$, the inverse of $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is $\frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$. Here $ad - bc$ is $i(1 - i) - i(1 + i) = 2$.

Thus the required inverse matrix is

$$\frac{1}{2} \begin{bmatrix} 1 - i & -i \\ -(1 + i) & i \end{bmatrix} = \begin{bmatrix} \frac{1}{2} - \frac{i}{2} & -\frac{i}{2} \\ -\frac{1}{2} - \frac{i}{2} & \frac{i}{2} \end{bmatrix}.$$

5. $W \subseteq V$ is a subset of V if $\mathbf{w}_1 + k\mathbf{w}_2 \in W$ for all $\mathbf{w}_1, \mathbf{w}_2 \in W$ and all scalars k .

$$W = \left\{ \mathbf{A} \in M_{n,n}(\mathbb{R}) \mid \mathbf{A} = \mathbf{A}^\top \right\}$$

Let

$$\mathbf{w}_1 = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}, \quad \mathbf{w}_2 = \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix}$$

$$\mathbf{w}_1 \in W \Rightarrow a_{ij} = a_{ji}, \mathbf{w}_2 \in W \Rightarrow b_{ij} = b_{ji}$$

$$\begin{aligned}
\mathbf{w}_1 + k\mathbf{w}_2 &= \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} + k \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix} \\
&= \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} + \begin{bmatrix} kb_{11} & kb_{12} & \dots & kb_{1n} \\ kb_{21} & kb_{22} & \dots & kb_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ kb_{n1} & kb_{n2} & \dots & kb_{nn} \end{bmatrix} \\
&= \begin{bmatrix} a_{11} + kb_{11} & a_{12} + kb_{12} & \dots & a_{1n} + kb_{1n} \\ a_{21} + kb_{21} & a_{22} + kb_{22} & \dots & a_{2n} + kb_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1} + kb_{n1} & a_{n2} + kb_{n2} & \dots & a_{nn} + kb_{nn} \end{bmatrix}
\end{aligned}$$

If the $(i, j)^{\text{th}}$ element of this matrix is c_{ij} , then $c_{ij} = a_{ij} + kb_{ij} = a_{ji} + kb_{ji} = c_{ji}$.

$\therefore \mathbf{w}_1 + k\mathbf{w}_2 \in W$ for each $\mathbf{w}_1, \mathbf{w}_2 \in W$, $k \in \mathbb{R}$ and hence W is a subspace.

$$\begin{aligned}
\text{Natural basis : } &\left\{ \begin{bmatrix} 0 & 1 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \vdots & 0 \end{bmatrix}, \right. \\
&\dots \begin{bmatrix} 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & 0 & 0 & \dots & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}, \dots \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & \dots & 1 & 0 \end{bmatrix}, \\
&\left. \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} \right\}
\end{aligned}$$

If $\mathbf{w} \in W$, $\mathbf{w} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{12} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{13} & a_{23} & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{1n} & a_{2n} & a_{3n} & \dots & a_{nn} \end{bmatrix} \quad (a_{ij} = a_{ji})$

$$\begin{aligned} \text{Then } \mathbf{w} = & a_{12} \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} + a_{13} \begin{bmatrix} 0 & 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 \end{bmatrix} \\ & + \dots + a_{1n} \begin{bmatrix} 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & 0 & 0 & \dots & 0 \end{bmatrix} + a_{23} \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} \\ & + \dots + a_{11} \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} + a_{22} \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} + \dots + a_{nn} \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} \end{aligned}$$

and so this set certainly spans W .

If we form

$$\begin{aligned} & k_{12} \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} + k_{13} \begin{bmatrix} 0 & 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 \end{bmatrix} + \dots + \\ & k_{n-1n} \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} + k_{11} \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} + \dots + k_{nn} \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} \\ \text{we get } & \begin{bmatrix} k_{11} & k_{12} & k_{13} & \dots & k_{1n} \\ k_{12} & k_{22} & k_{23} & \dots & k_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ k_{1n} & k_{2n} & k_{3n} & \dots & k_{nn} \end{bmatrix}. \end{aligned}$$

If this is to sum to $\mathbf{0}$, then $\begin{bmatrix} k_{11} & k_{12} & k_{13} & \dots & k_{1n} \\ k_{12} & k_{22} & k_{23} & \dots & k_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ k_{1n} & k_{2n} & k_{3n} & \dots & k_{nn} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}.$

i.e. each $k_{ij} = 0$, establishing linear independence. Hence, the stated set is a basis.

The number of elements in this basis is (the number of strictly upper diagonal elements) + (number of diagonal elements) $= \frac{1}{2}(n^2 - n) + n = \frac{1}{2}(n^2 + n) = \underline{\frac{1}{2}n(n+1)}$.

6.

$$R(T) = \left\{ \mathbf{w} \in V \mid \mathbf{w} = T(\mathbf{v}) \text{ for some } \mathbf{v} \in V \right\}$$

$$\ker(T) = \left\{ \mathbf{v} \in V \mid T(\mathbf{v}) = \mathbf{0} \right\}$$

(a) For T to be a linear transformation, $T(\mathbf{v}_1 + k\mathbf{v}_2) = T(\mathbf{v}_1) + kT(\mathbf{v}_2)$ for all $\mathbf{v}_1, \mathbf{v}_2 \in V, k \in \mathbb{R}$.

$$\mathbf{v}_1 = \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}$$

$$k\mathbf{v}_2 = k \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix} = \begin{bmatrix} kx_2 \\ ky_2 \\ kz_2 \end{bmatrix}$$

$$\therefore \mathbf{v}_1 + k\mathbf{v}_2 = \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} + \begin{bmatrix} kx_2 \\ ky_2 \\ kz_2 \end{bmatrix} = \begin{bmatrix} x_1 + kx_2 \\ y_1 + ky_2 \\ z_1 + kz_2 \end{bmatrix}$$

$$\begin{aligned} \therefore T(\mathbf{v}_1 + k\mathbf{v}_2) &= T \begin{bmatrix} x_1 + kx_2 \\ y_1 + ky_2 \\ z_1 + kz_2 \end{bmatrix} = \begin{bmatrix} 2(x_1 + kx_2) + (y_1 + ky_2) \\ (x_1 + kx_2) + 3(y_1 + ky_2) + (z_1 + kz_2) \\ (y_1 + ky_2) + 2(z_1 + kz_2) \end{bmatrix} \\ &= \begin{bmatrix} 2x_1 + y_1 + k(2x_2 + y_2) \\ x_1 + 3y_1 + z_1 + k(x_2 + 3y_2 + z_2) \\ y_1 + 2z_1 + k(y_2 + 2z_2) \end{bmatrix} = \begin{bmatrix} 2x_1 + y_1 \\ x_1 + 3y_1 + z_1 \\ y_1 + 2z_1 \end{bmatrix} + \begin{bmatrix} k(2x_2 + y_2) \\ k(x_2 + 3y_2 + z_2) \\ k(y_2 + 2z_2) \end{bmatrix} \\ &= \begin{bmatrix} 2x_1 + y_1 \\ x_1 + 3y_1 + z_1 \\ y_1 + 2z_1 \end{bmatrix} + k \begin{bmatrix} 2x_2 + y_2 \\ x_2 + 3y_2 + z_2 \\ y_2 + 2z_2 \end{bmatrix} = T \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} + kT \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}. \end{aligned}$$

i.e. $T(\mathbf{v}_1 + k\mathbf{v}_2) = T(\mathbf{v}_1) + kT(\mathbf{v}_2)$ and hence T is a linear transformation.

Let $\mathbf{v} \in \ker(T)$. Then $T(\mathbf{v}) = \mathbf{0}$.

$$\mathbf{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \Rightarrow T(\mathbf{v}) = T \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2x + y \\ x + 3y + z \\ y + 2z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\therefore \quad 2x + y = 0 \quad (1)$$

$$x + 3y + z = 0 \quad (2)$$

$$y + 2z = 0 \quad (3)$$

(3)-(1) $\Rightarrow z = x$. In (2), $x + 3y + x = 0 \Rightarrow 2x + 3y = 0$ (4). (4)-(1) $\Rightarrow y = 0$. Hence, $x = z = 0$ also.

$\therefore$ If $\mathbf{v} \in \ker(T)$, then $\mathbf{v} = \mathbf{0}$ i.e. $\ker(T) = \{\mathbf{0}\}$

$$\text{rank}(T) = \text{dimension of } k(T)$$

$$\text{nullity}(T) = \text{dimension of } \ker(T)$$

$$\text{rank and nullity formula: } \text{rank}(T) + \text{nullity}(T) = \dim(V)$$

$$\text{In this case, } \dim(V) = \dim(\mathbb{R}^3) = 3; \quad \text{nullity}(T) = \dim\{\mathbf{0}\} = 0.$$

$$\therefore \text{rank}(T) = 3 - 0 = 3.$$

If $T(\mathbf{v}_1) = T(\mathbf{v}_2)$, then $T(\mathbf{v}_1) - T(\mathbf{v}_2) = \mathbf{0}$. But since T is a linear transformation, $T(\mathbf{v}_1) - T(\mathbf{v}_2) = T(\mathbf{v}_1 - \mathbf{v}_2)$.

$$\therefore T(\mathbf{v}_1 - \mathbf{v}_2) = \mathbf{0}, \text{ so } \mathbf{v}_1 - \mathbf{v}_2 \in \ker(T).$$

$$\text{But } \ker(T) = \{\mathbf{0}\}, \text{ so } \mathbf{v}_1 - \mathbf{v}_2 = \mathbf{0} \quad \text{i.e. } \mathbf{v}_1 = \mathbf{v}_2.$$

(b) Let $\mathbf{u}$ represent the function f and $\mathbf{v}$ represent g .

$$\begin{aligned} T(\mathbf{u} + k\mathbf{v}) &= (f + kg)''(x) = f''(x) + kg''(x) \\ &= T(\mathbf{u}) + kT(\mathbf{v}). \end{aligned}$$

$\therefore T$ is a linear transformation.

$$\ker(T) = \left\{ \mathbf{v} \in V \mid T(\mathbf{v}) = \mathbf{0} \right\}$$

i.e. if $\mathbf{v}$ represents the function f , then $f''(x) \equiv 0$.

i.e. $\ker(T)$ comprises all continuous, linear functions of x .

7.

$$\begin{aligned} \det(\mathbf{A} - \lambda\mathbf{I}) &\Rightarrow \begin{vmatrix} 2 - \lambda & 1 & 0 \\ 1 & 3 - \lambda & 1 \\ 0 & 1 & 2 - \lambda \end{vmatrix} = 0 \\ C_1 \mapsto C_1 - C_3 : &\begin{vmatrix} 2 - \lambda & 1 & 0 \\ 1 & 3 - \lambda & 1 \\ -(2 - \lambda) & 1 & 2 - \lambda \end{vmatrix} = 0 \\ \text{i.e. } (2 - \lambda) &\begin{vmatrix} 1 & 1 & 0 \\ 0 & 3 - \lambda & 1 \\ -1 & 1 & 2 - \lambda \end{vmatrix} = 0. \end{aligned}$$

Expand by $R1$:

$$(2 - \lambda) \left\{ [(3 - \lambda)(2 - \lambda) - 1] - [0 + 1] \right\} = 0$$

$$(2 - \lambda)(\lambda^2 - 5\lambda + 4) = 0$$

$$(2 - \lambda)(\lambda - 4)(\lambda - 1) = 0.$$

$\therefore$ The eigenvalues are $\lambda_1 = 2$, $\lambda_2 = 4$, $\lambda_3 = 1$

$$\lambda_1 = 2 : \quad \mathbf{v} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & 1 & 0 \\ 1 & 3 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} 2\alpha \\ 2\beta \\ 2\gamma \end{bmatrix}$$

$$2\alpha + \beta = 2\alpha \quad (4)$$

$$\alpha + 3\beta + \gamma = 2\beta \quad (5)$$

$$\beta + 2\gamma = 2\gamma \quad (6)$$

$$(4) \ \& \ (6) \Rightarrow \beta = 0, \ (5) \Rightarrow \alpha = -\gamma$$

$$\therefore \text{An eigenvector is } \alpha \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \alpha \neq 0.$$

$$\lambda_2 = 4: \quad \mathbf{v} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & 1 & 0 \\ 1 & 3 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} 4\alpha \\ 4\beta \\ 4\gamma \end{bmatrix}$$

$$2\alpha + \beta = 4\alpha \quad (7)$$

$$\alpha + 3\beta + \gamma = 4\beta \quad (8)$$

$$\beta + 2\gamma = 4\gamma \quad (9)$$

$$(9) \Rightarrow \beta = 2\gamma, \ (7) \Rightarrow \beta = 2\alpha \quad \text{so } \alpha = \gamma, \beta = 2\alpha$$

$$\therefore \text{An eigenvector is } \alpha \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \alpha \neq 0.$$

$$\lambda_3 = 1: \quad \mathbf{v} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix}, \begin{bmatrix} 2 & 1 & 0 \\ 1 & 3 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix}$$

$$2\alpha + \beta = \alpha \quad (10)$$

$$\alpha + 3\beta + \gamma = \beta \quad (11)$$

$$\beta + 2\gamma = \gamma \quad (12)$$

$$(10) \Rightarrow \beta = -\alpha, \ (12) \Rightarrow \beta = -\gamma, \text{ in } (11) \ -\beta + 3\beta - \beta = \beta \quad \therefore \alpha = \gamma, \beta = -\alpha$$

$$\text{An eigenvector is } \alpha \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \alpha \neq 0.$$

Normalised eigenvectors are therefore

$$\mathbf{v}_1 = \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}; \quad \mathbf{v}_2 = \begin{bmatrix} 1/\sqrt{6} \\ 2/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}; \quad \mathbf{v}_3 = \begin{bmatrix} 1/\sqrt{3} \\ -1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}$$

$$\mathbf{P} = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{6} & 1/\sqrt{3} \\ 0 & 2/\sqrt{6} & -1/\sqrt{3} \\ -1/\sqrt{2} & 1/\sqrt{6} & 1/\sqrt{3} \end{bmatrix}$$

will be such that

$$\mathbf{P}^\top \mathbf{A} \mathbf{P} = \mathbf{D} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

NB other column orders of $\mathbf{P}$, $\mathbf{D}$ are possible.

$$Q = \mathbf{x}^\top \mathbf{A} \mathbf{x}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 3 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$\begin{aligned} \text{check : } \quad \mathbf{x}^\top \mathbf{A} \mathbf{x} &= \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 2 & 1 & 0 \\ 1 & 3 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \\ &= \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 2x_1 + x_2 \\ x_1 + 3x_2 + x_3 \\ x_2 + 2x_3 \end{bmatrix} \\ &= x_1(2x_1 + x_2) + x_2(x_1 + 3x_2 + x_3) + x_3(x_2 + 2x_3) \\ &= 2x_1^2 + 3x_2^2 + 2x_3^2 + 2x_1x_2 + 2x_2x_3. \end{aligned}$$

Set $\mathbf{x} = \mathbf{P} \mathbf{y}$

$$\begin{aligned} \mathbf{x}^\top \mathbf{A} \mathbf{x} &= (\mathbf{P} \mathbf{y})^\top \mathbf{A} \mathbf{P} \mathbf{y} = \mathbf{y}^\top \mathbf{P}^\top \mathbf{A} \mathbf{P} \mathbf{y} = \mathbf{y}^\top \mathbf{D} \mathbf{y} \\ &= \begin{bmatrix} y_1 & y_2 & y_3 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = 2y_1^2 + 4y_2^2 + y_3^2. \end{aligned}$$

$\therefore$ For this choice of $\mathbf{P}$, $\mathbf{D}$ (other choices are possible),

$$\begin{aligned} Q &= \alpha y_1^2 + \beta y_2^2 + \gamma y_3^2 \\ \alpha &= 2, \beta = 4, \gamma = 1 \end{aligned}$$

$\mathbf{y} = \mathbf{P}^{-1} \mathbf{x} = \mathbf{P}^\top \mathbf{x}$ (since $\mathbf{P}$ is orthogonal)

$$\text{i.e.} \quad \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & 0 & -1/\sqrt{2} \\ 1/\sqrt{6} & 2/\sqrt{6} & 1/\sqrt{6} \\ 1/\sqrt{3} & -1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\begin{aligned} y_1 &= \frac{1}{\sqrt{2}}(x_1 - x_3) \\ y_2 &= \frac{1}{\sqrt{6}}(x_1 + 2x_2 + x_3) \\ y_3 &= \frac{1}{\sqrt{3}}(x_1 - x_2 + x_3). \end{aligned}$$

8.

$$k_1 \begin{bmatrix} 1 \\ 0 \\ i \end{bmatrix} + k_2 \begin{bmatrix} 0 \\ 1 \\ i \end{bmatrix} + k_3 \begin{bmatrix} i \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow k_1 + ik_3 = 0 \quad (1)$$

$$k_2 + k_3 = 0 \quad (2)$$

$$ik_1 + ik_2 - k_3 = 0 \quad (3)$$

$(3) \times (-i) \Rightarrow k_1 + k_2 + ik_3 = 0$. Since $k_1 + ik_3 = 0$ (from (1)), this gives $k_2 = 0$. Hence, $k_3 = 0$ (from (2)) and then $k_1 = 0$ (from ((1))). $\therefore k_1 = k_2 = k_3 = 0$.

Hence, the vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ are independent.

Since V is three-dimensional, any set of three independent vectors is a basis. Such a set is $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$, which is therefore a basis.

Define $\mathbf{w}_1 = \mathbf{v}_1$ and choose $\mathbf{w}_2$ such that $\mathbf{w}_2 = \mathbf{v}_2 - \lambda \mathbf{v}_1$

$$\langle \mathbf{w}_2, \mathbf{w}_1 \rangle = \langle \mathbf{v}_2 - \lambda \mathbf{v}_1, \mathbf{v}_1 \rangle = \langle \mathbf{v}_2, \mathbf{v}_1 \rangle - \lambda \langle \mathbf{v}_1, \mathbf{v}_1 \rangle.$$

$\therefore$ choosing $\lambda = \frac{\langle \mathbf{v}_2, \mathbf{v}_1 \rangle}{\langle \mathbf{v}_1, \mathbf{v}_1 \rangle}$ will yield $\langle \mathbf{w}_2, \mathbf{w}_1 \rangle = 0$.

$$\langle \mathbf{v}_2, \mathbf{v}_1 \rangle = \underbrace{[0, 1 + i]}_{\mathbf{v}_2^\top} \underbrace{\begin{bmatrix} 1 \\ 0 \\ -i \end{bmatrix}}_{\bar{\mathbf{v}}_1} = +1$$

$$\langle \mathbf{v}_1, \mathbf{v}_1 \rangle = [1 \ 0 \ i] \begin{bmatrix} 1 \\ 0 \\ -i \end{bmatrix} = 2$$

$$\therefore \lambda = \frac{1}{2}$$

$$\mathbf{w}_2 = \begin{bmatrix} 0 \\ 1 \\ i \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ i \end{bmatrix} = \begin{bmatrix} -1/2 \\ 1 \\ i/2 \end{bmatrix}$$

$$\mathbf{w}_3 = \mathbf{v}_3 - \mu \mathbf{w}_2 - \nu \mathbf{w}_1$$

$$\langle \mathbf{w}_3, \mathbf{w}_2 \rangle = \langle \mathbf{v}_3, \mathbf{w}_2 \rangle - \mu \langle \mathbf{w}_2, \mathbf{w}_2 \rangle - \nu \langle \mathbf{w}_1, \mathbf{w}_2 \rangle$$

$\langle \mathbf{w}_1, \mathbf{w}_2 \rangle = 0$ since $\mathbf{w}_1$ and $\mathbf{w}_2$ are othogonal.

$$\therefore \langle \mathbf{w}_3, \mathbf{w}_2 \rangle = \langle \mathbf{v}_3, \mathbf{w}_2 \rangle - \mu \langle \mathbf{w}_2, \mathbf{w}_2 \rangle.$$

$\therefore$ Choosing $\mu = \langle \mathbf{v}_3, \mathbf{w}_2 \rangle / \langle \mathbf{w}_2, \mathbf{w}_2 \rangle$ guarantees that $\mathbf{w}_3, \mathbf{w}_2$ are orthogonal.

$$\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = \begin{bmatrix} i & 1 & -1 \end{bmatrix} \begin{bmatrix} -\frac{1}{2} \\ 1 \\ -i/2 \end{bmatrix} = -\frac{i}{2} + 1 + \frac{i}{2} = 1$$

$$\langle \mathbf{w}_2, \mathbf{w}_2 \rangle = \begin{bmatrix} -1/2 & 1 & i/2 \end{bmatrix} \begin{bmatrix} -1/2 \\ 1 \\ -i/2 \end{bmatrix} = \frac{1}{4} + 1 + \frac{1}{4} = \frac{3}{2}$$

$$\therefore \mu = 1/(3/2) = 2/3$$

$$\begin{aligned} \langle \mathbf{w}_3, \mathbf{w}_1 \rangle &= \langle \mathbf{v}_3, \mathbf{v}_1 \rangle - \lambda \langle \mathbf{w}_2, \mathbf{w}_1 \rangle - \nu \langle \mathbf{w}_1, \mathbf{w}_1 \rangle \\ &= \langle \mathbf{v}_3, \mathbf{v}_1 \rangle - \nu \langle \mathbf{w}_1, \mathbf{w}_1 \rangle \text{ since } \langle \mathbf{w}_2, \mathbf{w}_1 \rangle = 0. \end{aligned}$$

Choosing $\nu = \langle \mathbf{v}_3, \mathbf{v}_1 \rangle / \langle \mathbf{w}_1, \mathbf{w}_1 \rangle$ will guarantee that $0 = \langle \mathbf{w}_3, \mathbf{w}_1 \rangle$, so $\mathbf{w}_3$ and $\mathbf{w}_1$ are orthogonal.

$$\langle \mathbf{v}_3, \mathbf{v}_1 \rangle = \begin{bmatrix} i & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -i \end{bmatrix} = i + i = 2i$$

$$\langle \mathbf{w}_1, \mathbf{w}_1 \rangle = \begin{bmatrix} 1 & 0 & i \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -i \end{bmatrix} = 1 + 1 = 2$$

$$\therefore \nu = \frac{2i}{2} = i.$$

Then

$$\mathbf{w}_3 = \begin{bmatrix} i \\ 1 \\ -1 \end{bmatrix} - \frac{2}{3} \begin{bmatrix} -\frac{1}{2} \\ 1 \\ i/2 \end{bmatrix} - i \begin{bmatrix} 1 \\ 0 \\ i \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ -i/3 \end{bmatrix}.$$