

# Walking forward and backward in Euler schemes and random number generators

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In the memory of  
**Professor Grigori N. Milstein**  
**(1937-2023)**



Based on joint works with P. Cohort (Zeliade systems) and M. Mrad (University Paris Nord).

# 1 Reversing a Random Number Generator

## 1.1 Application/motivation

**Example:** Regression Monte-Carlo with low memory constraints

**Dynamic programming equation** (DPE) with  $N$  times:

$$\begin{aligned} \mathbf{Y}_i &= \mathbb{E} [\mathbf{g}_i(\mathbf{Y}_{i+1}, \dots, \mathbf{Y}_N, \mathbf{X}_i, \dots, \mathbf{X}_N) \mid \mathbf{X}_i], \quad i = N-1, \dots, 0, \\ \mathbf{Y}_N &= \mathbf{g}_N(\mathbf{X}_N), \end{aligned}$$

We want to estimate the function  $y_i$  such that  $Y_i = y_i(X_i)$ .

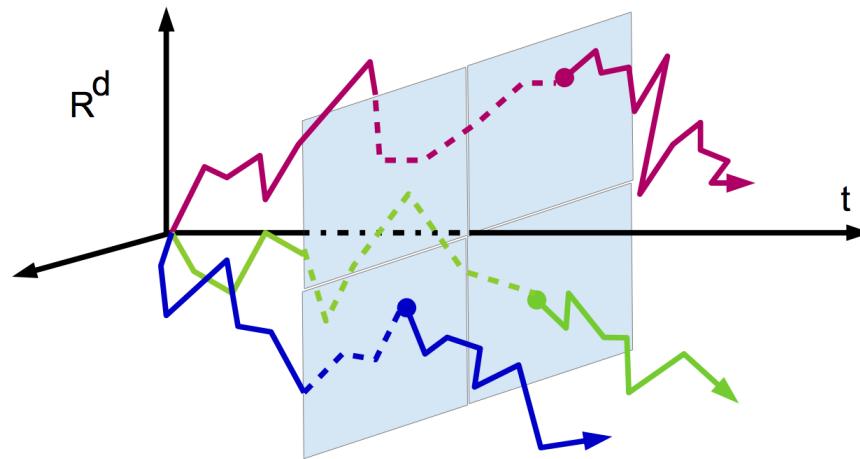
✓ **Optimal Stopping:**

- ▶ Value function:  $\mathbf{V}_i = \text{ess sup}_{\tau \in \mathcal{T}_{i,N}} \mathbb{E} [\mathbf{g}_\tau(\mathbf{X}_\tau) \mid \mathbf{X}_i]$ .
- ▶ Continuation value:  $\mathbf{Y}_i = \mathbb{E} [\mathbf{V}_{i+1} \mid \mathbf{X}_i]$  solves a DPE.

✓ **Semi-linear equations and Backward Stochastic differential equations also solves approximate DPE:**

- ▶ Non-linear PDE:  $\partial_t \mathbf{u} + \mathcal{L} \mathbf{u} + \mathbf{f}(\mathbf{u}, \sigma \nabla \mathbf{u}) = \mathbf{0}$ ,  $u(1, \cdot) = g(\cdot)$ .

**Regression Monte-Carlo:** [Longstaff-Schwartz '01, Belomestny-Milstein-Spokoiny '09, G'-Turkedejiev '16] value functions are computed using  $M$  simulations, and  $K$  basis functions (or Neural Networks with  $K$  parameters ...)



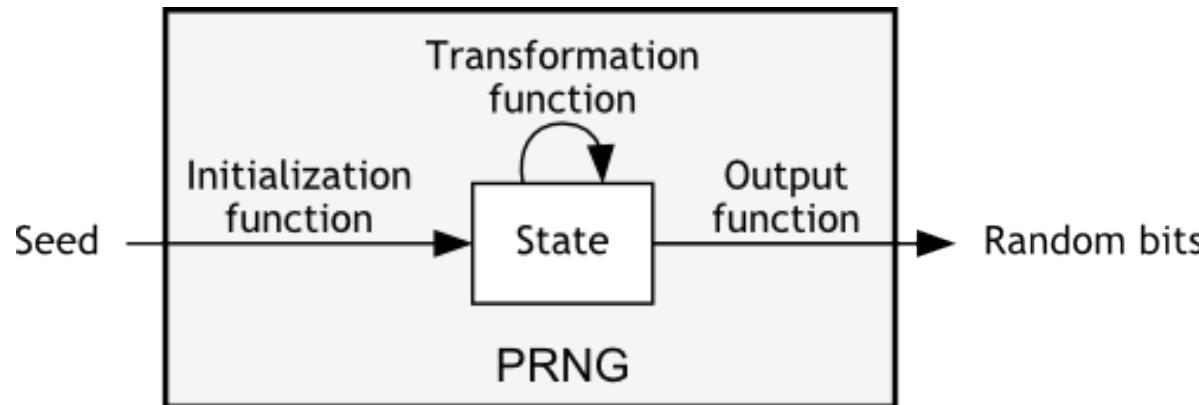
- ▷ **Convergence of the statistical error:** must have  $M \gg K$ .  
More precisely,  $\mathbf{M} \sim \mathbf{K}N^3$
- ▷ **Convergence of the approximation error:**  $K \sim N^{\alpha d}$
- ▷ **Memory constraints:**
  - ✓  $M$  paths of length  $N$ :  $\mathbf{M}N$
  - ✓  $N$  value functions:  $KN$

In [Aïd-Campi-Langrené-Pham '14], optimal investment in renewable energy.  
Time steps: 40 years and 2 decisions per day  $\Rightarrow N = 40 \times 2 \times 365 \approx 30000!!$

➡ **Impossible to store the simulations**

⇒ Sequential learning? or resampling data?

## 1.2 What is a Pseudo-RNG?



Schematic diagram of a pseudo-random number generator

Credits: <http://pit-claudel.fr/clement/>

### Examples.

- ✓ *Linear congruential generator*:  $x_{m+1} = ax_m + b \text{ MOD } L, \quad u_m = \frac{x_m}{L}$ .  
Ex:  $a = 7^5, b = 0$  et  $L = 2^{31} - 1 = 2147483647$ .
- ✓ *Mersenne Twister (1997)*: period  $2^{19937} - 1$
- ✓ *Xorshift (2003)*: period  $2^{1024} - 1$  (simple and fast)

## 1.3 Reversing the RNG

**PRNG sequence:**  $u_i = h(G^i(v_0))$  for some output function  $h$ , transformation function  $G$  and initialization state  $v_0$ .

**Is it possible to invert the sequence**

$$u_0 \curvearrowright u_1 \curvearrowright \dots \curvearrowright u_n \quad \text{to} \quad u_n \curvearrowright u_1 \curvearrowright \dots \curvearrowright u_0?$$

▷ **A classical example : the L'Ecuyer generator**

Classical example among the Multiple Recursive family [L'Ecuyer '88]

**Transformation function  $G$ :** defined by

$$G(x, y) := \begin{cases} 40014x \bmod 2147483563 \\ 40692y \bmod 2147483399 \end{cases}$$

**Generator output:**  $h(x, y) = (x - y)/2147483563 \bmod 1$ .

$m_1 := 2147483563$  and  $m_2 := 2147483399$  are prime numbers  $\Rightarrow G$  is invertible and  $G^{-1}$  is of the form of  $G$  (same computational complexity).

▷ An up-to-date example : the WELL generators

**WELL = Well Equidistributed Long-period Linear**

Belong to family of Linear Recurrence Modulo 2 generators [Panneton-L'Ecuyer '06].

**Transformation function:** based on linear recursions  $x_{n+1} = Ax_n$ , for a binary matrix  $A$ .

**Output function:**  $h(x_n) := Bx_n$  for a binary matrix  $B$ .

**Properties.**

- ✓ Generator reversible if  $A$  is invertible.
- ✓  $G$  and  $G^{-1}$  have similar complexity.
- ✓ Among the 17 WELL generators of [Panneton-L'Ecuyer '06], we found 11 invertible generators (e.g. WELL607a, 19937a, 23209b and 44497a)

## 2 Euler schemes: forward and backward (v1.0)

**IDEA:** inverting the RNG allows to backward resimulate the Brownian increments

No need anymore to store them

What about the SDE?

### 2.1 Forward scheme

$\mathbb{R}^d$ -valued diffusion on  $[0, 1]$ :  $dX_t = \mu(t, X_t)dt + \sigma(t, X_t)dW_t$ .

Forward Euler scheme at times  $t_i = i/N$ :

$$\vec{X}_0^N = \mathbf{x}, \quad \vec{X}_{t_{i+1}}^N = \vec{X}_{t_i}^N + \mu(t_i, \vec{X}_{t_i}^N) \frac{1}{N} + \sigma(t_i, \vec{X}_{t_i}^N) \Delta \mathbf{W}_{t_i}.$$

**Theorem.** Under Lipschitz assumptions,

$$\sup_{t \in [0,1]} \left\| \sup_{|\mathbf{x}| \leq \lambda} |\mathbf{X}_t(\mathbf{x}) - \vec{X}_t^N(\mathbf{x})| \right\|_{\mathbb{L}_q} \leq \frac{C}{N^{1/2}} \lambda^2, \quad \forall \lambda \geq 1.$$

## 2.2 Backward scheme

### Techniques of stochastic flows [Kunita '97]

- ✓ SDE  $X.(s, x)$  solution from initial condition  $x \in \mathbb{R}$  at time  $s > 0$ .
- ✓ Inverse flow  $\xi_{s,t}(x) := (X_{s,t})^{-1}(x)$ .

**Theorem ([Kunita '97]).**  $\xi$  is a semimartingale with **respect to  $t$**  for any  $(s, x)$ :

$$\begin{cases} d\xi_{s,t}(x) = -\text{Jac}(\xi_{s,t}(x)) [\mu(t, x) - \sum_j (\partial_j \sigma(t, x)).\sigma^j(t, x)] dt + \sigma(t, x) dW_t \\ \quad + \frac{1}{2} \sum_{i,j} \partial_{ij}^2 \xi_{s,t}(x) \sigma^i(t, x).\sigma^j(t, x) dt, \\ \xi_{s,s}(x) = x. \end{cases}$$

$\xi$  is a semimartingale with **respect to  $s$**  for any  $(t, x)$ :

$$\begin{cases} d\xi_{s,t}(x) = -[\mu(s, \xi_{s,t}(x)) - \sum_j (\partial_j \sigma(s, \xi_{s,t}(x))).\sigma^j(s, \xi_{s,t}(x))] ds \\ \quad - \sigma(s, \xi_{s,t}(x)) d\overleftarrow{W}_s, \\ \xi_{t,t}(x) = x. \end{cases}$$

## Definition (Backward Euler scheme (v1.0)).

$$\overleftarrow{X}_1^N = \overrightarrow{X}_1^N,$$

$$\begin{aligned} \overleftarrow{X}_{t_i}^N &= \overleftarrow{X}_{t_{i+1}}^N - \mu(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \frac{1}{N} - \sigma(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \Delta W_{t_i} \\ &\quad + \sum_j (\partial_j \sigma(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N)) . \sigma^j(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \frac{1}{N}. \end{aligned}$$

- 😊 Easy to simulate using backward regeneration of Brownian increments
- 😊 Avoid to invert the forward Euler transform

$$x \mapsto \overrightarrow{X}_{t_{i+1}}^N = x + \mu(t_i, x) \frac{1}{N} + \sigma(t_i, x) \Delta W_{t_i}.$$

- ✓ Convergence rate for  $\overleftarrow{X}_{t_i}^N - X_{t_i}$ ? or for  $\overleftarrow{X}_{t_i}^N - \overrightarrow{X}_{t_i}^N$ ?
- ❗ Non standard analysis: composition of dependent stochastic maps

## 2.3 Approximation of compound maps $F(\Theta)$

- ✓ a  $\mathcal{F} \otimes \mathcal{B}(\mathbb{R}^d)$ -measurable mapping  $(\omega, x) \in (\Omega, \mathbb{R}^d) \mapsto F(\omega, x) \in \mathbb{R}^{d'}$ , continuous in  $x$  for a.e.  $\omega$
- ✓  $\Theta : \Omega \mapsto \mathbb{R}^d$  be a  $\mathcal{F}$ -random variable.

**Our aim:** control in  $\mathbb{L}_q$  the error  $\omega \in \Omega \mapsto F^N(\omega, \Theta^N(\omega)) - F(\omega, \Theta(\omega))$

**In our case:**

- ✓  $\Theta^N = \vec{X}_1^N$  (forward evolution)
- ✓  $F^N = \overleftarrow{X}_{t_i}^N(y)$  (backward evolution from  $y$  at time 1)
- ✓  $F(\Theta) = X_{t_i}$

## General result for approximating $F(\Theta)$

**(H1)** For any  $q > 0$ ,  $\exists \alpha_q^{(\mathbf{H1})} \geq 0$  s.t.

$$\sup_{\lambda \geq 1} \lambda^{-\alpha_q^{(\mathbf{H1})}} \left\| \sup_{|x| \leq \lambda} |F(\cdot, x)| \right\|_{\mathbb{L}_q} < +\infty.$$

**(H2)**  $\exists \kappa \in (0, 1]$  such that  $\forall q > 0$ ,  $\exists \alpha_q^{(\mathbf{H2})} \geq 0$  s.t.

$$\sup_{\lambda \geq 1} \lambda^{-\alpha_q^{(\mathbf{H2})}} \left\| \sup_{x \neq y, |x| \leq \lambda, |y| \leq \lambda} \frac{|F(\cdot, y) - F(\cdot, x)|}{|y - x|^{\kappa}} \right\|_{\mathbb{L}_q} < +\infty.$$

**(H3)** For any  $q > 0$ ,  $\exists \alpha_q^{(\mathbf{H3})} \geq 0$  and a non-negative sequence  $(\varepsilon_q^{N, (\mathbf{H3})})_{N \geq 1}$  s.t.

$$\sup_{\lambda \geq 1} \lambda^{-\alpha_q^{(\mathbf{H3})}} \left\| \sup_{|x| \leq \lambda} |F^N(\cdot, x) - F(\cdot, x)| \right\|_{\mathbb{L}_q} \leq \varepsilon_{\mathbf{q}}^{N, (\mathbf{H3})}, \quad \forall N \geq 1.$$

**(H4)** For any  $q > 0$ , there exists a non-negative sequence  $(\varepsilon_q^{N,(\mathbf{H4b})})_{N \geq 1}$  s.t.

$$\sup_{N \geq 1} \left[ \|\Theta\|_{\mathbb{L}_q} \vee \|\Theta^N\|_{\mathbb{L}_q} \right] < +\infty,$$

$$\|\Theta^N - \Theta\|_{\mathbb{L}_q} \leq \varepsilon_{\mathbf{q}}^{N,(\mathbf{H4b})}, \quad \forall N \geq 1.$$

**Theorem (general result).** Assume **(H1-H2-H3-H4)**. Then for any  $q > 0$  and any  $q_2 > q$ , there is a constant  $c$  independent on  $N$  such that

$$\|\mathbf{F}^{\mathbf{N}}(\boldsymbol{\Theta}^{\mathbf{N}}) - \mathbf{F}(\boldsymbol{\Theta})\|_{\mathbb{L}_{\mathbf{q}}} \leq c \left( \varepsilon_{2\mathbf{q}}^{N,(\mathbf{H3})} + [\varepsilon_{\kappa\mathbf{q}_2}^{N,(\mathbf{H4b})}]^\kappa \right).$$

**Corollary (rule of thumb).** If

- ✓  $F_N - F = O(N^{-\gamma_F})$  in any  $L_q$ ,
- ✓  $\Theta^N - \Theta = O(N^{-\gamma_\theta})$  in any  $L_q$ ,

the order of  $L_q$ -convergence of  $F^N(\Theta^N) - F(\Theta)$  is  $\gamma_{\mathbf{F}} \wedge (\kappa\gamma_\theta)$ .

## Application to backward Euler scheme

**Corollary (Backward Euler vs forward diffusion).** For any  $q \geq 1$ ,

$$\sup_{t_i \leq 1} \left\| \overleftarrow{X}_{t_i}^N - X_{t_i} \right\|_{\mathbb{L}_q} = O(N^{-1/2}).$$

One can not improve the convergence order  $1/2$ .

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**Corollary (Backward Euler vs forward Euler).** For any  $q \geq 1$ ,

$$\sup_{t_i \leq 1} \left\| \overleftarrow{X}_{t_i}^N - \overrightarrow{X}_{t_i}^N \right\|_{\mathbb{L}_q} = O(N^{-1/2}).$$

- ✓ Can we improve the accuracy in retrieving  $\overrightarrow{X}_{t_i}^N$  by backward generation?
- ✓ Rate  $N^{-1}$ ?
- 😊 It would mean that the backward generation brings a smaller error than the forward generation.

### 3 Backward Euler scheme (v2.0)

#### 3.1 Definition

$$\overleftarrow{X}_1^N = \overrightarrow{X}_1^N,$$

$$\begin{aligned} \overleftarrow{X}_{t_i}^N &= \overleftarrow{X}_{t_{i+1}}^N - \mu(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \frac{1}{N} - \sigma(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \Delta W_{t_i} \\ &\quad + \text{Jac}(\sigma(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \Delta W_{t_i}) \sigma(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \Delta W_{t_i}. \end{aligned}$$

In (v1.0), the blue term was  $\sum_j (\partial_j \sigma(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N)) \cdot \sigma^j(t_{i+1}, \overleftarrow{X}_{t_{i+1}}^N) \frac{1}{N}$ .

#### 3.2 Convergence rate and CLT

**Theorem (a.s. error).** For any  $\eta > 0$ ,  $\exists C_\eta : \Omega \rightarrow \mathbb{R}^+$  s.t.

$$\sup_{t_i \leq 1} \left| \overleftarrow{X}_{t_i}^N - \overrightarrow{X}_{t_i}^N \right| \leq C_\eta N^{-1+\eta}, \quad \forall N \geq 1, \text{ a.s.}$$

**Theorem (Functional CLT).** For some processes  $a$  and  $b$  and an extra Brownian motion  $B$ , the error  $\mathcal{E}_t^N = \overleftarrow{X}_t^N - \overrightarrow{X}_t^N$  satisfies

$$\left\{ N \mathcal{E}_t^N : 0 \leq t \leq 1 \right\} \xrightarrow{\text{d}} \int_0^1 a_s ds + \int_0^1 b_s dB_s.$$

SKETCH OF PROOF: ERROR  $\mathcal{E}_k = \overleftarrow{X}_{t_k}^N - \overrightarrow{X}_{t_k}^N$

**Proposition.** For any  $1 \leq i \leq d$  and any integer  $k \leq N - 1$ , the  $i$ -th coordinate of the error approximation satisfies

$$\begin{aligned} \mathcal{E}_k^i &= \mathcal{E}_{k+1}^i + \bar{a}_k^i \mathcal{E}_{k+1} + \mathcal{E}_{k+1}^\top b_k^i \mathcal{E}_{k+1} + \mathcal{E}_{k+1}^\top \left( \sum_{j=1}^d c_k^{i,j} \mathcal{E}_{k+1}^j \right) \mathcal{E}_{k+1} \\ &\quad + d_k^i (\Delta W_k^3) + e_k^i (\Delta W_k^1) \Delta t + f_k^i (\Delta W_k^4) + g_k^i (\Delta W_k^2) \Delta t + h_k^i \Delta t^2 + \delta_k^i, \end{aligned}$$

where

$$\sup_{0 \leq k \leq N-1} \|\delta_k^i\|_{\mathbb{L}_q} = O(N^{-5/2}), \quad \forall q \geq 1,$$

and

$$\left\{ \begin{array}{ll} b_k^i & := \frac{1}{2} \left[ \mathcal{H}(\nabla(\sigma^i \Delta W_k)(\sigma \Delta W_k)) - \mathcal{H}(\mu^i) \Delta t - \mathcal{H}(\sigma^i \Delta W_k) \right. \\ & \quad \left. - \sum_{j=1}^d \partial_j \mathcal{H}(\sigma^i \Delta W_k)(\sigma^j \Delta W_k) \right], \\ c_k^{i,j} & := -\frac{1}{6} \partial_j \mathcal{H}(\sigma^i \Delta W_k), \\ \bar{a}_k^i & := \nabla[\nabla(\sigma^i \Delta W_k)(\sigma \Delta W_k)] - \nabla \mu^i \Delta t - \nabla(\sigma^i \Delta W_k) \\ & + (\mu \Delta t + \sigma \Delta W_k)^\top \left( \mathcal{H}(\nabla(\sigma^i \Delta W_k)(\sigma \Delta W_k)) - \mathcal{H}(\mu^i) \Delta t - \mathcal{H}(\sigma^i \Delta W_k) \right) \\ & - \frac{1}{2} (\sigma \Delta W_k)^\top \left( \sum_{j=1}^d \partial_j \mathcal{H}(\sigma^i \Delta W_k)(\sigma^j \Delta W_k) \right), \quad \text{for } 1 \leq i \leq d \\ d_k(\Delta W_k^3) & := \left[ (\nabla[\nabla(\sigma^i \Delta W_k)(\sigma \Delta W_k)] - \frac{1}{2} (\sigma \Delta W_k)^\top \mathcal{H}(\sigma^i \Delta W_k))(\sigma \Delta W_k) \right]_{1 \leq i \leq d}, \\ e_k(\Delta W_k^1) & := -\nabla \mu(\sigma \Delta W_k) - \nabla(\sigma \Delta W_k) \mu, \\ f_k(\Delta W_k^4) & := \left[ (\sigma \Delta W_k)^\top \left( \frac{1}{2} \mathcal{H}(\nabla(\sigma^i \Delta W_k)(\sigma \Delta W_k)) \right. \right. \\ & \quad \left. \left. - \frac{1}{6} \sum_{j=1}^d \partial_j \mathcal{H}(\sigma^i \Delta W_k)(\sigma^j \Delta W_k) \right) (\sigma \Delta W_k) \right]_{1 \leq i \leq d}, \\ g_k(\Delta W_k^2) & := \left[ \left( \nabla[\nabla(\sigma^i \Delta W_k)(\sigma \Delta W_k)] \mu - \frac{1}{2} (\sigma \Delta W_k)^\top \mathcal{H}(\mu^i)(\sigma \Delta W_k) \right. \right. \\ & \quad \left. \left. - (\sigma \Delta W_k)^\top \mathcal{H}(\sigma^i \Delta W_k) \mu \right) \right]_{1 \leq i \leq d}, \\ h_k & := [-\nabla(\mu^i) \mu]_{1 \leq i \leq d}. \end{array} \right.$$

## PROPAGATING ERRORS

$$\begin{aligned}\mathcal{E}_k^i &= \mathcal{E}_{k+1}^i + \bar{a}_k^i \mathcal{E}_{k+1} + \mathcal{E}_{k+1}^\top b_k^i \mathcal{E}_{k+1} + \mathcal{E}_{k+1}^\top \left( \sum_{j=1}^d c_k^{i,j} \mathcal{E}_{k+1}^j \right) \mathcal{E}_{k+1} \\ &\quad + d_k^i (\Delta W_k^3) + e_k^i (\Delta W_k^1) \Delta t + f_k^i (\Delta W_k^4) + g_k^i (\Delta W_k^2) \Delta t + h_k^i \Delta t^2 + \delta_k^i.\end{aligned}$$

- 😊 Initialization:  $\mathcal{E}_N = 0$
- 😊 Local errors: using martingale arguments, we have

$$\begin{aligned}\sum_k (d_k^i (\Delta W_k^3) + e_k^i (\Delta W_k^1) \Delta t + f_k^i (\Delta W_k^4) + g_k^i (\Delta W_k^2) \Delta t + h_k^i \Delta t^2 + \delta_k^i) \\ = O_{\mathbb{L}_q}(N^{-1})\end{aligned}$$

- ❗ Error propagation: application of Gronwall lemma does not work because of the quadratic/cubic term in  $\mathcal{E}_{k+1}$

Instead,

1. Write carefully  $\mathcal{E}_k$  with local errors between  $k + 1$  and  $N$
2. Use that

$$\sup_{t_i \leq 1} \|\mathcal{E}_i\|_{\mathbb{L}_q} = O(N^{-1/2}), \quad \forall q \geq 1,$$

to get (Borel Cantelli)

$$\sup_{t_i \leq 1} |\mathcal{E}_i| = O(N^{-1/2+\eta}) \quad a.s. \quad \text{for any given } \eta > 0.$$

3. Plug these a.s. bounds into the one-step error equations to get

$$\sup_{t_i \leq 1} |\mathcal{E}_i| = O(N^{-\kappa}) \quad a.s. \quad \text{for a } \kappa \in (1/2, 1).$$

4. Iterate to get  $\sup_{t_i \leq 1} |\mathcal{E}_i| = O(N^{-1+\eta}) \quad a.s.$

5. Finally, prove

$$\sup_{t_i \leq 1} |\mathcal{E}_i - L_i| = O(N^{-\kappa'}) \quad a.s.$$

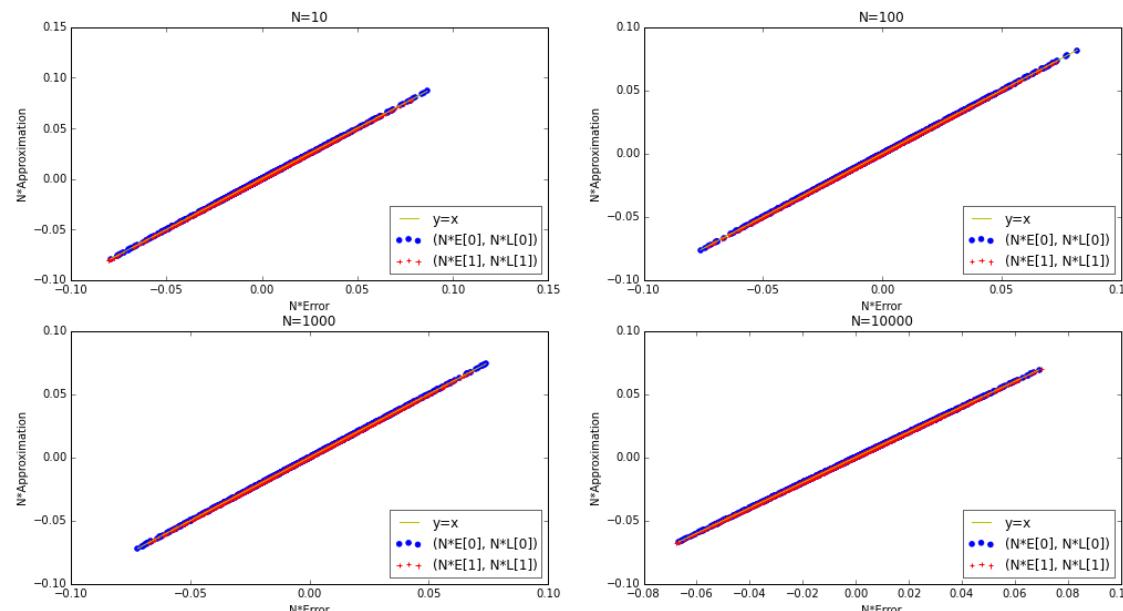
for a  $\kappa' \in (1, 3/2)$ , where  $L_i$  gives the weak-limit at rate  $N$ .

### 3.3 Numerical results

- ✓ 10000 paths
- ✓ empirical joint distribution of  $(N\mathcal{E}_0^N, NL_0^N)$
- ✓ examples in dimension 2

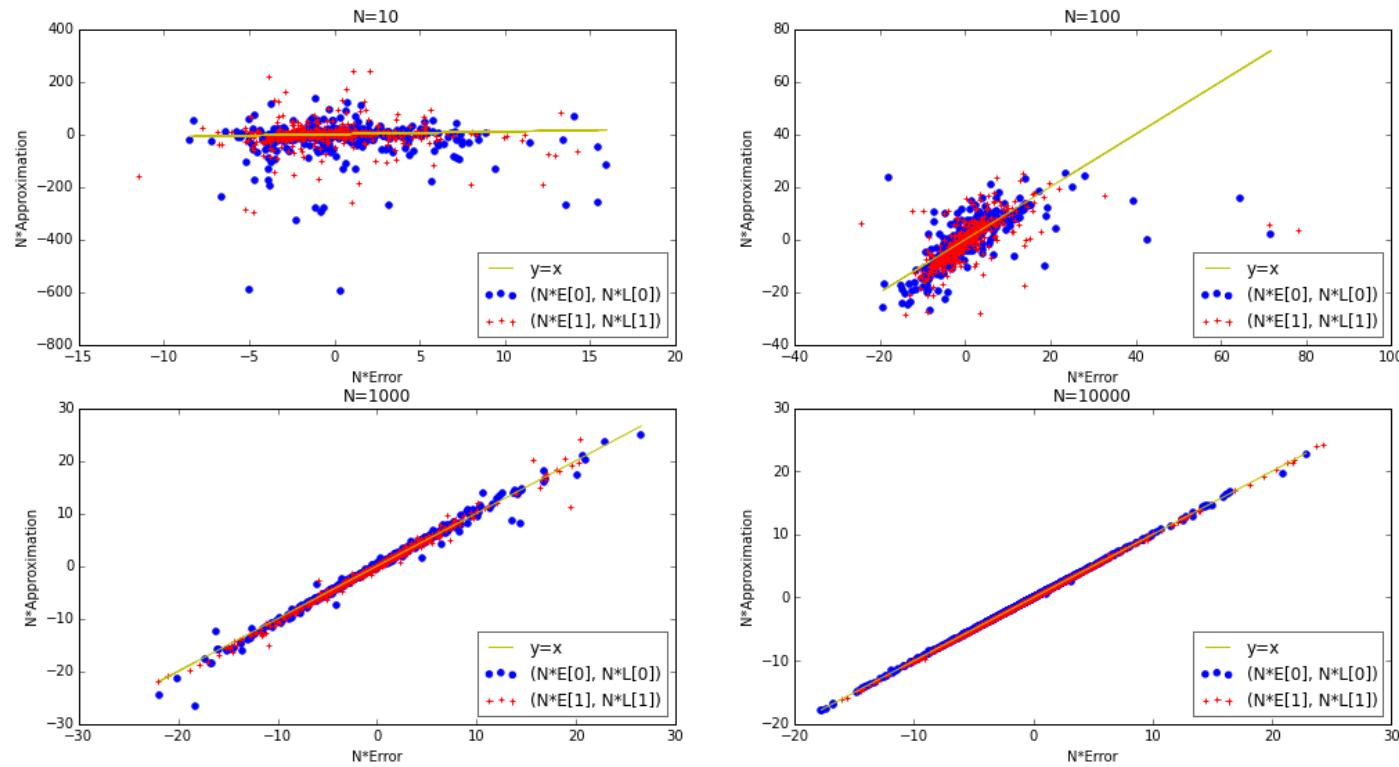
**Linear SDE:** standard non correlated two-dimensional Black&Scholes case

$$\mu(x) = (0, 0), \quad \sigma(x) = \begin{pmatrix} 0.2x_0 & 0 \\ 0 & 0.2x_1 \end{pmatrix}, \quad x_0 = (1, 1).$$



## Non linear SDE 1:

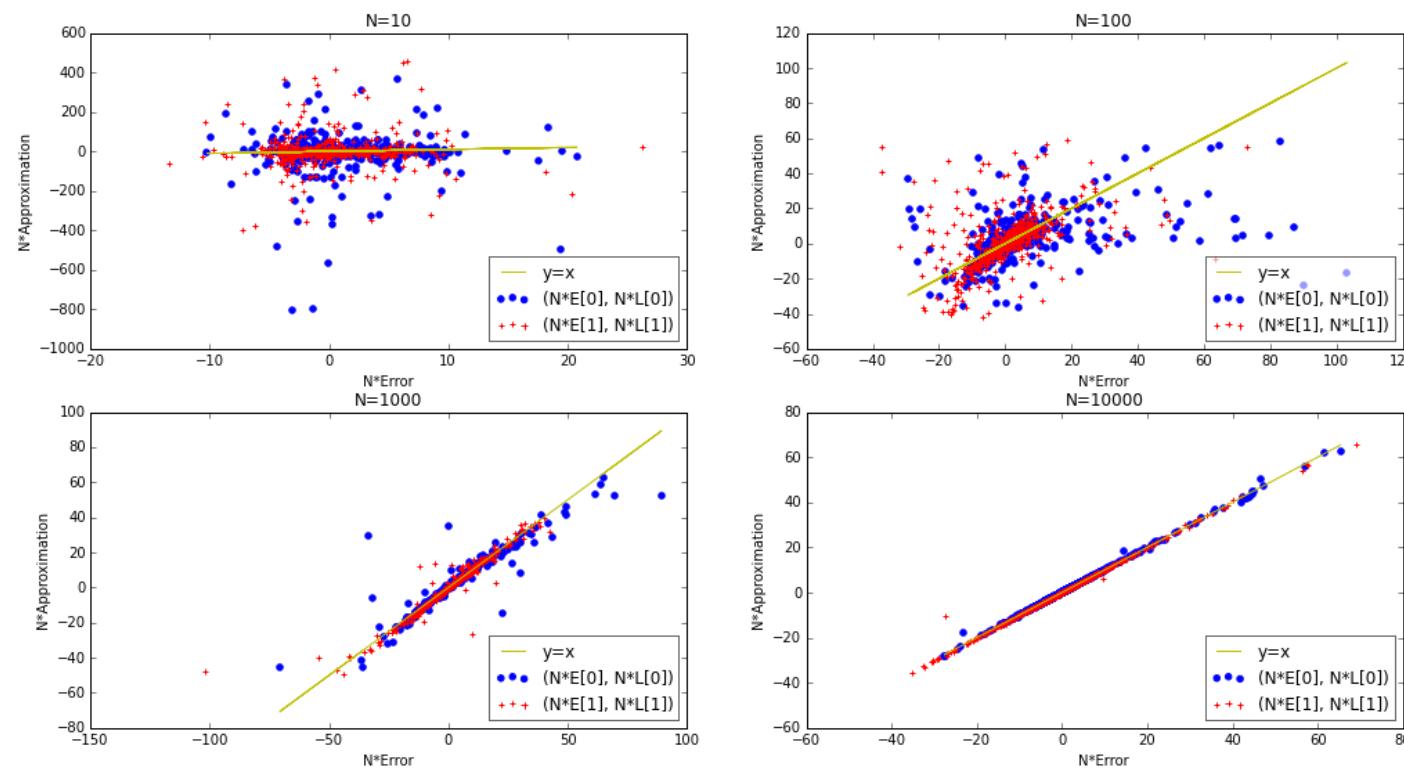
$$\mu(x) = (0, 0), \quad \sigma(x) = \begin{pmatrix} 0.2 x_0(1 + \sin(2\pi x_0)) & 0.2 x_0(1 + \cos(2\pi x_1)) \\ 0.2 x_1(1 + \cos(2\pi x_0)) & 0.2 x_1(1 + \sin(2\pi x_1)) \end{pmatrix}, \quad Y_0 = (1, 1).$$



## Non linear SDE 2:

$$\mu(x) = (0.2 x_0(1 + \sin(2\pi x_0)), 0.2 x_0(1 + \sin(2\pi x_1)))$$

$$\sigma(x) = \begin{pmatrix} 0.2 x_0(1 + \sin(2\pi x_0)) & 0.2 x_0(1 + \cos(2\pi x_1)) \\ 0.2 x_1(1 + \cos(2\pi x_0)) & 0.2 x_1(1 + \sin(2\pi x_1)) \end{pmatrix}, \quad Y_0 = (1, 1).$$



## 4 Conclusion

- ✓ Accurate resampling of Euler schemes using backward regeneration of Brownian increments
- ✓ Convergence rates:
  - 😊  $N^{-1^-}$  in a.s. sense
  - 😊  $N^{-1}$  for weak convergence
  - 🙁  $N^{-?}$  for strong convergence
- ✓ Useful for Regression Monte Carlo algorithms with strong memory constraints
- ✓ Future work: generalization to Milstein scheme

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